### Localisation principles for variant H-measures

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Joint work with Marko Erceg, Ivan Ivec, Martin Lazar, Marin Mišur and Darko Mitrović







#### H-measures and variants

H-measures Existence of H-measures Localisation principle

#### **H**-distributions

Existence Localisation principle Other variants

# One-scale H-measures

Semiclassical measures One-scale H-measures Localisation principle

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Start from  $u_n \longrightarrow 0$  in  $L^2(\mathbf{R}^d)$ ,  $\varphi \in C_c(\mathbf{R}^d)$ , and take the Fourier transform:

$$\widehat{\varphi u_n}(\boldsymbol{\xi}) = \int_{\mathbf{R}^d} e^{-2\pi i \mathbf{x} \cdot \boldsymbol{\xi}}(\varphi u_n)(\mathbf{x}) d\mathbf{x}$$

As  $\varphi u_n$  is supported on a fixed compact set K, so  $|\widehat{\varphi u_n}(\boldsymbol{\xi})| \leq C$ . Furthermore,  $u_n \longrightarrow 0$ , and from the definition  $\widehat{\varphi u_n}(\boldsymbol{\xi}) \longrightarrow 0$  pointwise. By the Lebesgue dominated convergence theorem on bounded sets, we get  $\widehat{\varphi u_n} \longrightarrow 0$  strong, i.e. strongly in  $L^2_{loc}(\mathbf{R}^d)$ .

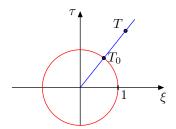
On the other hand, by the Plancherel theorem:  $\|\widehat{\varphi u_n}\|_{L^2(\mathbf{R}^d)} = \|\varphi u_n\|_{L^2(\mathbf{R}^d)}$ . If  $\varphi u_n \neq 0$  in  $L^2(\mathbf{R}^d)$ , then  $\widehat{\varphi u_n} \neq 0$ ; some information must go to infinity. How does it go to infinity in various directions? Take  $\psi \in C(S^{d-1})$ , and consider:

$$\lim_{n} \int_{\mathbf{R}^{d}} \psi(\boldsymbol{\xi}/|\boldsymbol{\xi}|) |\widehat{\varphi u_{n}}|^{2} d\boldsymbol{\xi} = \int_{\mathbf{S}^{d-1}} \psi(\boldsymbol{\xi}) d\nu_{\varphi}(\boldsymbol{\xi}) d\boldsymbol{\xi}$$

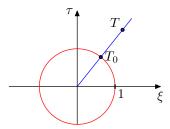
The limit is a linear functional in  $\psi$ , thus an integral over the sphere of some nonegativne Radon measure (a bounded sequence of Radon measures has an accumulation point), which depends on  $\varphi$ . How does it depent on  $\varphi$ ?

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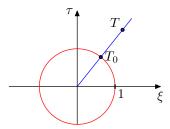
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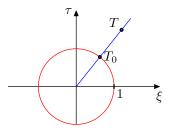
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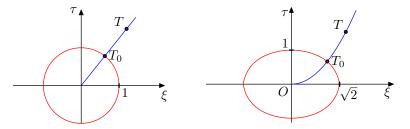
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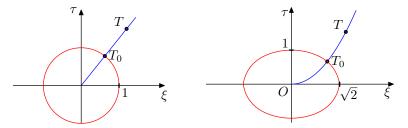
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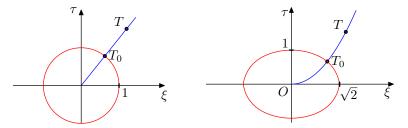
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Multiplication by  $b \in L^{\infty}(\mathbf{R}^2)$ , a bounded operator  $M_b$  on  $L^2(\mathbf{R}^2)$ :  $(M_b u)(\mathbf{x}) := b(\mathbf{x})u(\mathbf{x})$ ,

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The precise scaling is contained in the projections, not the surface. Now we can state the main theorem, where we use the notation

$$\mathsf{v} \cdot \mathsf{u} := \sum v_i \bar{u}_i \;, \quad (\mathsf{v} \otimes \mathsf{u}) \mathsf{a} := (\mathsf{a} \cdot \mathsf{u}) \mathsf{v} \;, \text{while} \quad (f \boxtimes g)(\mathbf{x}, \boldsymbol{\xi}) := f(\mathbf{x}) g(\boldsymbol{\xi}) \;.$$

**Theorem.** If  $u_n \longrightarrow 0$  in  $L^2(\mathbf{R}^d; \mathbf{C}^r)$ , then there exists a subsequence and a complex matrix Radon measure  $\mu$  on

 $\mathbf{R}^d \times \mathbf{S}^{d-1}$ 

such that for any  $arphi_1, arphi_2 \in \mathrm{C}_0(\mathbf{R}^d)$  and

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$$\begin{split} &\lim_{n'} \int_{\mathbf{R}^d} \widehat{\varphi_1 \mathbf{u}_{n'}} \otimes \widehat{\varphi_2 \mathbf{u}_{n'}}(\psi \circ p \ ) \, d\boldsymbol{\xi} = \langle \boldsymbol{\mu}, (\varphi_1 \bar{\varphi}_2) \boxtimes \psi \rangle \\ &= \int_{\mathbf{R}^d \times \mathbb{S}^{d-1}} \varphi_1(\mathbf{x}) \bar{\varphi}_2(\mathbf{x}) \psi(\boldsymbol{\xi}) \, d\bar{\boldsymbol{\mu}}(\mathbf{x}, \boldsymbol{\xi}) \end{split}$$

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Taking sequences in  $L^2_{loc}(\Omega; \mathbf{C}^r)$ , one gets unbounded Radon measures (i.e. distributions of order zero) as H-measures. It holds:  $u_n \longrightarrow 0$  in  $L^2_{loc}(\mathbf{R}^d; \mathbf{C}^r)$  if and only if  $\boldsymbol{\mu} = \mathbf{0}$ .

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There are some other variants (E. Ju. Panov, D. Mitrović & I. Ivec, M. Erceg & I. Ivec, ...).

#### Important lemma

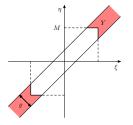
Lemma. (first commutation — Luc Tartar) If  $b \in C_0(\mathbf{R}^d)$  and  $a \in L^{\infty}(\mathbf{R}^d)$  satisfy the condition

 $(\forall \, \rho, \varepsilon \in \mathbf{R}^+) (\exists \, M \in \mathbf{R}^+) \quad |a(\boldsymbol{\xi}) - a(\boldsymbol{\eta})| \leqslant \varepsilon \; (\text{a.e.} \; (\boldsymbol{\xi}, \boldsymbol{\eta}) \in Y(M, \rho)) \;,$ 

then  $C := [\mathcal{A}_a, M_b]$  is a compact operator on  $L^2(\mathbf{R}^d)$ .

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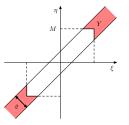
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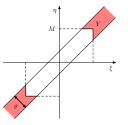
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Similar results were obtained and used earlier in the theory of pseudodifferential operators.

# Localisation principle for classical H-measures

$$\sum_{k=1}^{d} \partial_k(\mathbf{A}^k \mathbf{u} ) + \mathbf{B} \mathbf{u} = \mathbf{f} , \qquad \mathbf{A}^k \in \mathrm{C}_b(\mathbf{R}^d; \mathrm{M}_{l \times r})$$

Assume:

$$u_n \xrightarrow{L^2} 0$$
, and defines  $\mu$   
 $f_n \xrightarrow{H_{loc}^-} 0$ .

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$$\sum_{k=1}^{d} \partial_k(\mathbf{A}^k \mathbf{u}_n) + \mathbf{B} \mathbf{u}_n = \mathbf{f}_n \quad , \qquad \mathbf{A}^k \in \mathbf{C}_b(\mathbf{R}^d; \mathbf{M}_{l \times r})$$

Assume:

$$\begin{split} \mathsf{u}_n & \stackrel{\mathrm{L}^2}{\longrightarrow} \mathsf{0} \;, \qquad \text{and defines } \mu \\ \mathsf{f}_n & \stackrel{\mathrm{H}_{\mathrm{loc}}^{-1}}{\longrightarrow} \mathsf{0} \;. \end{split}$$

**Theorem.** (localisation principle) If u<sub>n</sub> satisfies:

$$\sum_{k=1}^{d} \partial_k \left( \mathbf{A}^k \mathbf{u}_n \right) \longrightarrow \mathbf{0} \qquad \text{in } \mathrm{H}_{\mathrm{loc}}^{-1} (\mathbf{R}^d; \mathbf{C}^r) ,$$

then for  $\mathbf{p}(\mathbf{x}, \boldsymbol{\xi}) := \sum_{k=1}^{d} \xi_k \mathbf{A}^k(\mathbf{x})$  on  $\Omega \times S^{d-1}$  one has:  $\mathbf{p}(\mathbf{x}, \boldsymbol{\xi}) \boldsymbol{\mu}^\top = \mathbf{0}$ .

### Localisation principle for classical H-measures

$$\sum_{k=1}^{d} \partial_k(\mathbf{A}^k \mathbf{u}_n) + \mathbf{B} \mathbf{u}_n = \mathbf{f}_n \quad , \qquad \mathbf{A}^k \in \mathbf{C}_b(\mathbf{R}^d; \mathbf{M}_{l \times r})$$

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**Theorem.** (localisation principle) If u<sub>n</sub> satisfies:

$$\sum_{k=1}^{d} \partial_k \big( \mathbf{A}^k \mathbf{u}_n \big) \longrightarrow \mathbf{0} \qquad \text{in } \mathrm{H}^{-1}_{\mathrm{loc}} (\mathbf{R}^d; \mathbf{C}^r) \;,$$

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Thus, if l = r, the support of H-measure  $\mu$  is contaned in the set  $\{(\mathbf{x}, \boldsymbol{\xi}) \in \Omega \times S^{d-1} : \det \mathbf{p}(\mathbf{x}, \boldsymbol{\xi}) = 0\}$  of points where  $\mathbf{p}$  is a singular matrix.

The localisation principle is behind most of the known applications (e.g. to the small-amplitude homogenisation). It contains a generalisation of compactness by compensation to variable coefficients.

Localisation principle for parabolic H-measures

In the parabolic case the details become more involved.

Anisotropic Sobolev spaces ( $s \in \mathbf{R}$ ;  $k_p(\tau, \boldsymbol{\xi}) := \sqrt[4]{1 + (2\pi\tau)^2 + (2\pi|\boldsymbol{\xi}|)^4}$ )

$$\mathrm{H}^{\frac{s}{2},s}(\mathbf{R}^{1+d}):=\left\{u\in\mathcal{S}':k_p^s\hat{u}\in\mathrm{L}^2(\mathbf{R}^{1+d})\right\}\,.$$

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**Theorem.** (localisation principle) Let  $u_n \longrightarrow 0$  in  $L^2(\mathbf{R}^{1+d}; \mathbf{C}^r)$ , uniformly compactly supported in t, satisfy  $(s \in \mathbf{N})$ 

$$\sqrt{\partial_t}^s(\mathbf{A}^0\mathbf{u}_n) + \sum_{|\boldsymbol{\alpha}|=s} \partial_{\mathbf{x}}^{\boldsymbol{\alpha}}(\mathbf{A}^{\boldsymbol{\alpha}}\mathbf{u}_n) \longrightarrow 0 \quad \text{strongly in} \quad \mathbf{H}_{\mathrm{loc}}^{-\frac{s}{2},-s}(\mathbf{R}^{1+d}) \ ,$$

where  $\mathbf{A}^0, \mathbf{A}^{\alpha} \in C_b(\mathbf{R}^{1+d}; M_{l \times r}(\mathbf{C}))$ , for some  $l \in \mathbf{N}$ , while  $\sqrt{\partial}_t$  is a pseudodifferential operator with symbol  $\sqrt{2\pi i \tau}$ , i.e.

$$\sqrt{\partial}_t u = \overline{\mathcal{F}}\left(\sqrt{2\pi i\tau}\,\hat{u}(\tau)\right).$$

Then for a parabolic H-measure  $\mu$  associated to (a sub)sequence (of)  $(u_n)$  one has

$$\left((\sqrt{2\pi i\tau})^{s}\mathbf{A}^{0}+\sum_{|\boldsymbol{\alpha}|=s}(2\pi i\boldsymbol{\xi})^{\boldsymbol{\alpha}}\mathbf{A}^{\boldsymbol{\alpha}}\right)\boldsymbol{\mu}^{\top}=\mathbf{0}$$

Good bounds in the  $L^p$  case: the Hörmander-Mihlin theorem

 $\psi: \mathbf{R}^d \to \mathbf{C}$  is a Fourier multiplier on  $\mathrm{L}^p(\mathbf{R}^d)$  if

$$\bar{\mathcal{F}}(\psi \mathcal{F}(\theta)) \in \mathrm{L}^p(\mathbf{R}^d) , \qquad \text{for } \theta \in \mathcal{S}(\mathbf{R}^d),$$

and

$$\mathcal{S}(\mathbf{R}^d) \ni \theta \mapsto \bar{\mathcal{F}}(\psi \mathcal{F}(\theta)) \in \mathbf{L}^p(\mathbf{R}^d)$$

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**Theorem.** [Hörmander-Mihlin] Let  $\psi \in L^{\infty}(\mathbf{R}^d)$  have partial derivatives of order less than or equal to  $\kappa = [\frac{d}{2}] + 1$ . If for some k > 0

$$(\forall r > 0)(\forall \boldsymbol{\alpha} \in \mathbf{N}_0^d) \qquad |\boldsymbol{\alpha}| \leqslant \kappa \implies \int_{\frac{r}{2} \leqslant |\boldsymbol{\xi}| \leqslant r} |\partial^{\boldsymbol{\alpha}} \psi(\boldsymbol{\xi})|^2 d\boldsymbol{\xi} \leqslant k^2 r^{d-2|\boldsymbol{\alpha}|} ,$$

then for any  $p \in \langle 1, \infty \rangle$  and the associated multiplier operator  $\mathcal{A}_{\psi}$  there exists a  $C_d$  (depending only on the dimension d) such that

$$\|\mathcal{A}_{\psi}\|_{\mathbf{L}^{p}\to\mathbf{L}^{p}} \leqslant C_{d} \max\left\{p, \frac{1}{p-1}\right\} (k+\|\psi\|_{\infty}) .$$

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For  $\psi \in C^{\kappa}(S^{d-1})$ , extended by homogeneity to  $\mathbf{R}^{d}_{*}$ , we can take  $k = \|\psi\|_{C^{\kappa}}$ .

**Theorem.** [N.A. & D. Mitrović (2011)] If  $u_n \longrightarrow 0$  in  $L^p(\mathbf{R}^d)$  and  $v_n \stackrel{*}{\longrightarrow} v$  in  $L^q(\mathbf{R}^d)$  for some  $q \ge \max\{p', 2\}$ , then there exist subsequences  $(u_{n'}), (v_{n'})$  and a complex valued distribution  $\mu \in \mathcal{D}'(\mathbf{R}^d \times \mathbf{S}^{d-1})$  of order not more than  $\kappa = [d/2] + 1$  in  $\boldsymbol{\xi}$ , such that for every  $\varphi_1, \varphi_2 \in C_c^{\infty}(\mathbf{R}^d)$  and  $\psi \in C^{\kappa}(\mathbf{S}^{d-1})$  we have:

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The H-distribution would correspond to a non-diagonal block for an H-measure.

 $\psi \in C^{\kappa}(S^{d-1})$  satisfies the conditions of the Hörmander-Mihlin theorem. Therefore,  $\mathcal{A}_{\psi}$  and  $M_{\varphi}$  are bounded operators on  $L^{p}(\mathbf{R}^{d})$ , for any  $p \in \langle 1, \infty \rangle$ . We are interested in the properties of their commutator,  $C = \mathcal{A}_{\psi}M_{\varphi} - M_{\varphi}\mathcal{A}_{\psi}$ .

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If q < r, we can apply the classical interpolation inequality:

$$||Cv_n||_q \leq ||Cv_n||_2^{\alpha} ||Cv_n||_r^{1-\alpha}$$
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For the most interesting case, where q = r, we need a better result: the Krasnosel'skij theorem (a variant of Riesz-Thorin theorem).

We still need a lemma on *compactness* of uniformly bounded bilinear forms, and an application of the Schwartz kernel theorem.

**Theorem.** Take  $u_n \rightarrow 0$  in  $L^p(\mathbf{R}^d)$ ,  $f_n \rightarrow 0$  in  $W_{loc}^{-1,q}(\mathbf{R}^d)$ , for some  $q \in \langle 1, d \rangle$ , such that

 $\operatorname{div}\left(\mathsf{a}(\mathbf{x})u_n(\mathbf{x})\right) = f_n(\mathbf{x}) \;.$ 

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 $\mathsf{div}\left(\mathsf{a}(\mathbf{x})u_n(\mathbf{x})\right) = f_n(\mathbf{x}) \;.$ 

Take an arbitrary  $(v_n)$  bounded in  $L^{\infty}(\mathbf{R}^d)$ , and by  $\mu$  denote the *H*-distribution corresponding to a subsequence of  $(u_n)$  and  $(v_n)$ . Then

$$(\mathbf{a}(\mathbf{x})\cdot\boldsymbol{\xi})\mu(\mathbf{x},\boldsymbol{\xi})=0$$

in the sense of distributions on  $\mathbf{R}^d \times S^{d-1}$ ,  $(\mathbf{x}, \boldsymbol{\xi}) \mapsto \mathsf{a}(\mathbf{x}) \cdot \boldsymbol{\xi}$  being the symbol of the linear PDO with  $C_0^{\kappa}$  coefficients.

**Theorem.** Take  $u_n \rightharpoonup 0$  in  $L^p(\mathbf{R}^d)$ ,  $f_n \rightarrow 0$  in  $W^{-1,q}_{loc}(\mathbf{R}^d)$ , for some  $q \in \langle 1, d \rangle$ , such that

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In order to prove the theorem, we need a particular multiplier, the so called (Marcel) Riesz potential  $I_1 := \mathcal{A}_{|2\pi\boldsymbol{\xi}|^{-1}}$ , and the Riesz transforms  $R_j := \mathcal{A}_{\frac{\xi_j}{i|\boldsymbol{\xi}|}}$ . Note that

$$\int I_1(\phi)\partial_j g = \int (R_j\phi)g, \ g \in \mathcal{S}(\mathbf{R}^d).$$

Using the density argument and that  $R_j$  is bounded from  $L^p(\mathbf{R}^d)$  to itself, we conclude  $\partial_j I_1(\phi) = -R_j(\phi)$ , for  $\phi \in L^p(\mathbf{R}^d)$ .

**Theorem.** Take  $u_n \rightharpoonup 0$  in  $L^p(\mathbf{R}^d)$ ,  $f_n \rightarrow 0$  in  $W^{-1,q}_{loc}(\mathbf{R}^d)$ , for some  $q \in \langle 1, d \rangle$ , such that

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(an application suggested by Darko Mitrović) For scalar conservation law with discontinuous flux, the most up to date existence result for the equation

 $u_t + \operatorname{div} \mathsf{f}(t, \mathbf{x}, u) = 0$ 

is obtained under the assumptions

$$\max_{\lambda \in \mathbf{R}} |\mathsf{f}(t, \mathbf{x}, \lambda)| \in L^{2+\varepsilon}(\mathbf{R}^d_+) \ .$$

Using the H-distributions, it is poossible to prove an existence result for the given equation under the assumption

$$\max_{\lambda \in \mathbf{R}} |\mathbf{f}(t, \mathbf{x}, \lambda)| \in L^{1+\varepsilon}(\mathbf{R}^d_+) .$$

N.A. & I. Ivec: extension to Lebesgue spaces with mixed norm M. Lazar & D. Mitrović: applications to velocity averaging M. Mišur & D. Mitrović: a form of compactness by compensation J. Aleksić, S. Pilipović, I. Vojnović (preprint): in S - S' setting F. Rindler (ARMA, 2015): microlocal compactness forms

**Theorem.** If  $\mathbf{u}_n \to \mathbf{0}$  in  $L^2(\Omega; \mathbf{C}^r)$ ,  $\omega_n \to 0^+$ , then there exist a subsequence  $(\mathbf{u}_{n'})$  and  $\boldsymbol{\mu}_{sc}^{(\omega_n)} \in \mathcal{M}_b(\Omega \times \mathbf{R}^d; M_r(\mathbf{C}))$  such that for any  $\varphi_1, \varphi_2 \in C_c^{\infty}(\Omega)$  and  $\psi \in \mathcal{S}(\mathbf{R}^d)$ 

$$\lim_{n'} \int_{\mathbf{R}^d} \left( \widehat{\varphi_1 \mathbf{u}_{n'}}(\boldsymbol{\xi}) \otimes \widehat{\varphi_2 \mathbf{u}_{n'}}(\boldsymbol{\xi}) \right) \psi(\omega_{n'} \boldsymbol{\xi}) \, d\boldsymbol{\xi} = \left\langle \boldsymbol{\mu}_{sc}^{(\omega_n)}, \varphi_1 \overline{\varphi}_2 \boxtimes \psi \right\rangle.$$

Measure  $\mu_{sc}^{(\omega_n)}$  we call the semiclassical measure with characteristic length  $(\omega_n)$  corresponding to the (sub)sequence  $(u_n)$ .

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#### Theorem.

$$\mathsf{u}_n \stackrel{\mathrm{L}^2_{\mathrm{loc}}}{\longrightarrow} \mathsf{0} \iff \boldsymbol{\mu}_{sc}^{(\omega_n)} = \mathbf{0} \quad \& \quad (\mathsf{u}_n) \text{ is } (\omega_n) - \textit{oscillatory}$$

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 $\begin{array}{ll} \text{Definition } (\mathfrak{u}_n) \text{ is } (\omega_n) \text{-socillatory if} \\ (\forall \, \varphi \in \mathrm{C}^\infty_c(\Omega)) \quad \lim_{R \to \infty} \limsup_n \int_{|\boldsymbol{\xi}| \geqslant \frac{R}{\omega_n}} |\widehat{\varphi \mathfrak{u}_n}(\boldsymbol{\xi})|^2 \, d\boldsymbol{\xi} = 0 \, . \end{array}$ 

#### Theorem.

$$u_n \stackrel{\mathrm{L}^2_{\mathrm{loc}}}{\longrightarrow} \mathsf{0} \iff \mu_{sc}^{(\omega_n)} = \mathsf{0} \quad \& \quad (\mathsf{u}_n) \text{ is } (\omega_n) - \textit{oscillatory} \, .$$

# Localisation principle for semiclassical measures

Let  $\Omega \subseteq \mathbf{R}^d$  open,  $m \in \mathbf{N}$ ,  $u_n \rightharpoonup 0$  in  $\mathrm{L}^2_{\mathrm{loc}}(\Omega; \mathbf{C}^r)$  and

$$\mathbf{P}_n \mathbf{u}_n := \sum_{|\boldsymbol{\alpha}| \leqslant m} \varepsilon_n^{|\boldsymbol{\alpha}|} \partial_{\boldsymbol{\alpha}} (\mathbf{A}^{\boldsymbol{\alpha}} \mathbf{u}_n) = \mathbf{f}_n \quad \text{in } \Omega \,,$$

where

- $\varepsilon_n \to 0^+$
- $\mathbf{A}^{\boldsymbol{\alpha}} \in C(\Omega; M_r(\mathbf{C}))$
- $f_n \longrightarrow 0$  in  $L^2_{loc}(\Omega; \mathbf{C}^r)$ . Then we have

$$\mathbf{p}\boldsymbol{\mu}_{sc}^{\top}=\mathbf{0}\,,$$

where  $\mathbf{p}(\mathbf{x}, \boldsymbol{\xi}) = \sum_{|\boldsymbol{\alpha}| \leq m} \boldsymbol{\xi}^{\boldsymbol{\alpha}} \mathbf{A}^{\boldsymbol{\alpha}}(\mathbf{x})$ , and  $\boldsymbol{\mu}_{sc}$  is semiclassical measure with characteristic length  $(\varepsilon_n)$ , corresponding to  $(u_n)$ .

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 $\operatorname{supp} \boldsymbol{\mu}_{sc} \subseteq \{ (\mathbf{x}, \boldsymbol{\xi}) \in \Omega \times \mathbf{R}^d : \det \mathbf{p}(\mathbf{x}, \boldsymbol{\xi}) = 0 \},\$ 

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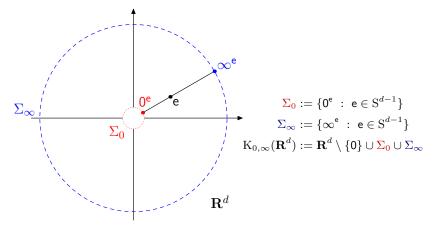
- $\varepsilon_n \to 0^+$
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Problem:  $\mu_{sc} = 0$  is not enough for the strong convergence!

# Compatification of $\mathbf{R}^d \setminus \{\mathbf{0}\}$



 $\begin{array}{ll} \text{Corollary.} & \textbf{a} ) \operatorname{C}_0(\mathbf{R}^d) \subseteq \operatorname{C}(\operatorname{K}_{0,\infty}(\mathbf{R}^d)). \\ \textbf{b} ) \ \psi \in \operatorname{C}(\operatorname{S}^{d-1}), \ \psi \circ \boldsymbol{\pi} \in \operatorname{C}(\operatorname{K}_{0,\infty}(\mathbf{R}^d)), \ \text{where} \ \boldsymbol{\pi}(\boldsymbol{\xi}) = \boldsymbol{\xi}/|\boldsymbol{\xi}|. \end{array}$ 

**Theorem.** If  $\mathbf{u}_n \to 0$  in  $L^2(\Omega; \mathbf{C}^r)$ ,  $\omega_n \to 0^+$ , then there exists a subsequence  $(\mathbf{u}_{n'})$  and  $\boldsymbol{\mu}_{sc}^{(\omega_n)} \in \mathcal{M}_b(\Omega \times \mathbf{R}^d; M_r(\mathbf{C}))$  such that for any  $\varphi_1, \varphi_2 \in \mathbf{C}_c^{\infty}(\Omega)$  and  $\psi \in \mathcal{S}(\mathbf{R}^d)$ 

$$\lim_{n'} \int_{\mathbf{R}^d} \left( (\widehat{\varphi_1 \mathbf{u}_{n'}})(\boldsymbol{\xi}) \otimes (\widehat{\varphi_2 \mathbf{u}_{n'}})(\boldsymbol{\xi}) \right) \psi(\omega_{n'} \boldsymbol{\xi}) \, d\boldsymbol{\xi} = \left\langle \boldsymbol{\mu}_{sc}, \varphi_1 \bar{\varphi}_2 \boxtimes \psi \right\rangle \, .$$

Measure  $\mu_{sc}^{(\omega_n)}$  is called the semiclassical measure with characteristic length  $(\omega_n)$  corresponding to the (sub)sequence  $(u_n)$ .

**Theorem.** If  $u_n \rightarrow 0$  in  $L^2(\Omega; \mathbf{C}^r)$ ,  $\omega_n \rightarrow 0^+$ , then there exists a subsequence  $(u_{n'})$  and  $\boldsymbol{\mu}_{K_{0,\infty}}^{(\omega_n)} \in \mathcal{M}_b(\Omega \times K_{0,\infty}(\mathbf{R}^d); M_r(\mathbf{C}))$  such that for any  $\varphi_1, \varphi_2 \in C_0(\Omega)$  and  $\psi \in C(K_{0,\infty}(\mathbf{R}^d))$ 

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LUC TARTAR: The general theory of homogenization: A personalized introduction, Springer, 2009. LUC TARTAR: Multi-scale H-measures, Discrete and Continuous Dynamical Systems, S 8 (2015) 77–90.

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# Idea of the proof

Tartar's approach:

- $\mathbf{v}_n(\mathbf{x}, x^{d+1}) := \mathbf{u}_n(\mathbf{x}) e^{\frac{2\pi i x^{d+1}}{\omega_n}} \rightarrow \mathbf{0} \text{ in } \mathbf{L}^2_{\mathrm{loc}}(\Omega \times \mathbf{R}; \mathbf{C}^r)$
- $\boldsymbol{\nu}_H \in \mathcal{M}(\Omega \times \mathbf{R} \times \mathrm{S}^d; \mathrm{M}_{\mathrm{r}}(\mathbf{C}))$
- $\mu_{{
  m K}_{0,\infty}}^{(\omega_n)}$  is obtained from  $u_H$  (suitable projection in  $x^{d+1}$  and  $\xi_{d+1}$ )

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### Our approach:

• First commutation lemma:

**Lemma.** Let  $\psi \in C(K_{0,\infty}(\mathbf{R}^d))$ ,  $\varphi \in C_0(\mathbf{R}^d)$ ,  $\omega_n \to 0^+$ , and denote  $\psi_n(\boldsymbol{\xi}) := \psi(\omega_n \boldsymbol{\xi})$ . Then the commutator can be expressed as a sum

$$C_n := [B_{\varphi}, \mathcal{A}_{\psi_n}] = \tilde{C}_n + K \,,$$

where K is a compact operator on  $L^2(\mathbf{R}^d)$ , while  $\tilde{C}_n \longrightarrow 0$  in the operator norm on  $\mathcal{L}(L^2(\mathbf{R}^d))$ .

• standard procedure: (a variant of) the kernel theorem, separability, ...

# Some properties of $oldsymbol{\mu}_{\mathrm{K}_{0,\infty}}$

Theorem.

$$\begin{array}{ll} \textbf{a)} & \boldsymbol{\mu}_{\mathrm{K}_{0,\infty}}^{*} = \boldsymbol{\mu}_{\mathrm{K}_{0,\infty}} , & \boldsymbol{\mu}_{\mathrm{K}_{0,\infty}} \geqslant \mathbf{0} \\ \textbf{b)} & \mathbf{u}_{n}^{\mathrm{L}_{\mathrm{loc}}^{2}} \mathbf{0} & \Longleftrightarrow & \boldsymbol{\mu}_{\mathrm{K}_{0,\infty}} = \mathbf{0} \\ \textbf{c)} & \mathrm{tr} \boldsymbol{\mu}_{\mathrm{K}_{0,\infty}}(\Omega \times \Sigma_{\infty}) = 0 & \Longleftrightarrow & (\mathbf{u}_{n}) \text{ is } (\omega_{n}) - \textit{oscillatory} \end{array}$$

# Some properties of $oldsymbol{\mu}_{\mathrm{K}_{0,\infty}}$

### Theorem.

a) 
$$\mu_{\mathrm{K}_{0,\infty}}^* = \mu_{\mathrm{K}_{0,\infty}}, \quad \mu_{\mathrm{K}_{0,\infty}} \ge \mathbf{0}$$
  
b)  $u_n \frac{\mathrm{L}_{\mathrm{loc}}^2}{2} \mathbf{0} \quad \Longleftrightarrow \quad \mu_{\mathrm{K}_{0,\infty}} = \mathbf{0}$   
c)  $\mathrm{tr} \mu_{\mathrm{K}_{0,\infty}}(\Omega \times \Sigma_{\infty}) = \mathbf{0} \quad \Longleftrightarrow \quad (\mathbf{u}_n) \text{ is } (\omega_n) - \text{oscillatory}$ 

**Theorem.**  $\varphi_1, \varphi_2 \in \mathcal{C}_c(\Omega)$ ,  $\psi \in \mathcal{C}_0(\mathbf{R}^d)$ ,  $\tilde{\psi} \in \mathcal{C}(\mathcal{S}^{d-1})$ ,  $\omega_n \to 0^+$ ,

$$\begin{array}{ll} \textbf{a)} & \langle \boldsymbol{\mu}_{\mathrm{K}_{0,\infty}}^{(\omega_n)}, \varphi_1 \bar{\varphi_2} \boxtimes \psi \rangle & = \langle \boldsymbol{\mu}_{sc}^{(\omega_n)}, \varphi_1 \bar{\varphi_2} \boxtimes \psi \rangle \,, \\ \textbf{b)} & \langle \boldsymbol{\mu}_{\mathrm{K}_{0,\infty}}^{(\omega_n)}, \varphi_1 \bar{\varphi_2} \boxtimes \tilde{\psi} \circ \boldsymbol{\pi} \rangle & = \langle \boldsymbol{\mu}_H, \varphi_1 \bar{\varphi_2} \boxtimes \tilde{\psi} \rangle \,, \end{array}$$

where  $\pi({m \xi})={m \xi}/|{m \xi}|.$ 

Let  $\Omega \subseteq \mathbf{R}^d$  open,  $m \in \mathbf{N}$ ,  $\mathsf{u}_n 
ightarrow \mathsf{0}$  in  $\mathrm{L}^2_{\mathrm{loc}}(\Omega; \mathbf{C}^r)$  and

$$\sum_{l \leqslant |\boldsymbol{\alpha}| \leqslant m} \varepsilon_n^{|\boldsymbol{\alpha}| - l} \partial_{\boldsymbol{\alpha}}(\mathbf{A}^{\boldsymbol{\alpha}} \mathbf{u}_n) = \mathbf{f}_n \quad \text{in } \Omega \,,$$

where

- $l \in 0..m$
- $\varepsilon_n \to 0^+$
- $\mathbf{A}^{\boldsymbol{\alpha}} \in C(\Omega; M_r(\mathbf{C}))$
- $f_n \in \mathrm{H}^{-m}_{\mathrm{loc}}(\Omega; \mathbf{C}^r)$  such that

$$(\forall \varphi \in \mathcal{C}_{c}^{\infty}(\Omega)) \qquad \frac{\widehat{\varphi f_{n}}}{1 + \sum_{s=l}^{m} \varepsilon_{n}^{s-l} |\boldsymbol{\xi}|^{s}} \longrightarrow 0 \quad \text{in} \quad \mathcal{L}^{2}(\mathbf{R}^{d}; \mathbf{C}^{r}) \qquad (\mathcal{C}(\varepsilon_{n}))$$

Let 
$$\Omega \subseteq \mathbf{R}^d$$
 open,  $m \in \mathbf{N}$ ,  $\mathsf{u}_n 
ightarrow \mathsf{0}$  in  $\mathrm{L}^2_{\mathrm{loc}}(\Omega; \mathbf{C}^r)$  and

$$\sum_{l \leqslant |\boldsymbol{\alpha}| \leqslant m} \varepsilon_n^{|\boldsymbol{\alpha}| - l} \partial_{\boldsymbol{\alpha}}(\mathbf{A}^{\boldsymbol{\alpha}} \mathbf{u}_n) = \mathbf{f}_n \quad \text{in } \Omega \,,$$

where

- $l \in 0..m$
- $\varepsilon_n \to 0^+$
- $\mathbf{A}^{\boldsymbol{\alpha}} \in C(\Omega; M_r(\mathbf{C}))$
- $f_n \in H^{-m}_{loc}(\Omega; \mathbf{C}^r)$  such that

$$(\forall \varphi \in \mathcal{C}_{c}^{\infty}(\Omega)) \qquad \frac{\widehat{\varphi f_{n}}}{1 + \sum_{s=l}^{m} \varepsilon_{n}^{s-l} |\boldsymbol{\xi}|^{s}} \longrightarrow 0 \quad \text{in} \quad \mathcal{L}^{2}(\mathbf{R}^{d}; \mathbf{C}^{r}) \qquad (\mathcal{C}(\varepsilon_{n}))$$

**Lemma.** a) ( $C(\varepsilon_n)$ ) is equivalent to

$$(\forall \varphi \in \mathcal{C}^{\infty}_{c}(\Omega)) \qquad \frac{\widehat{\varphi \mathbf{f}_{n}}}{1 + |\boldsymbol{\xi}|^{l} + \varepsilon_{n}^{m-l}|\boldsymbol{\xi}|^{m}} \longrightarrow \mathbf{0} \quad \textit{in} \quad \mathcal{L}^{2}(\mathbf{R}^{d}; \mathbf{C}^{r}) \,.$$

 $b) (\exists k \in l..m) f_n \longrightarrow 0 \text{ in } H^{-k}_{loc}(\Omega; \mathbf{C}^r) \implies (\varepsilon_n^{k-l} f_n) \text{ satisfies (} C(\varepsilon_n)).$ 

$$\begin{split} &\sum_{l\leqslant |\boldsymbol{\alpha}|\leqslant m} \varepsilon_n^{|\boldsymbol{\alpha}|-l} \partial_{\boldsymbol{\alpha}}(\mathbf{A}^{\boldsymbol{\alpha}} \mathbf{u}_n) = \mathbf{f}_n \quad \text{in } \Omega \,, \\ (\forall \, \varphi \in \mathbf{C}_c^{\infty}(\Omega)) & \quad \frac{\widehat{\varphi} \mathbf{f}_n}{1 + \sum_{s=l}^m \varepsilon_n^{s-l} |\boldsymbol{\xi}|^s} \longrightarrow 0 \quad \text{in } \quad \mathbf{L}^2(\mathbf{R}^d; \mathbf{C}^r) \,. \quad (\mathbf{C}(\varepsilon_n)) \end{split}$$

**Theorem.** [Tartar (2009)] Under previous assumptions and l = 1, one-scale *H*-measure  $\mu_{K_{0,\infty}}$  with characteristic length  $(\varepsilon_n)$  corresponding to  $(u_n)$  satisfies

$$\operatorname{supp}\left(\mathbf{p}\boldsymbol{\mu}_{\mathrm{K}_{0,\infty}}^{\top}\right)\subseteq\Omega\times\Sigma_{0}\,,$$

where

$$\mathbf{p}(\mathbf{x},\boldsymbol{\xi}) := \sum_{1 \leq |\boldsymbol{\alpha}| \leq m} (2\pi i)^{|\boldsymbol{\alpha}|} \frac{\boldsymbol{\xi}^{\boldsymbol{\alpha}}}{|\boldsymbol{\xi}| + |\boldsymbol{\xi}|^m} \mathbf{A}^{\boldsymbol{\alpha}}(\mathbf{x}).$$

$$\begin{split} &\sum_{l\leqslant |\boldsymbol{\alpha}|\leqslant m} \varepsilon_n^{|\boldsymbol{\alpha}|-l} \partial_{\boldsymbol{\alpha}} (\mathbf{A}^{\boldsymbol{\alpha}} \mathbf{u}_n) = \mathbf{f}_n \quad \text{in } \Omega \,, \\ (\forall \, \varphi \in \mathbf{C}_c^{\infty}(\Omega)) & \quad \frac{\widehat{\varphi} \mathbf{f}_n}{1 + \sum_{s=l}^m \varepsilon_n^{s-l} |\boldsymbol{\xi}|^s} \longrightarrow 0 \quad \text{in } \quad \mathbf{L}^2(\mathbf{R}^d; \mathbf{C}^r) \,. \quad (\mathbf{C}(\varepsilon_n)) \end{split}$$

**Theorem.** [N.A., Erceg, Lazar (2015)] Under previous assumptions, one-scale H-measure  $\mu_{K_{0,\infty}}$  with characteristic length  $(\varepsilon_n)$  corresponding to  $(u_n)$  satisfies

$$\mathbf{p}\boldsymbol{\mu}_{\mathrm{K}_{0,\infty}}^{\top} = \mathbf{0},$$

where

$$\mathbf{p}(\mathbf{x},\boldsymbol{\xi}) := \sum_{l \leq |\boldsymbol{\alpha}| \leq m} (2\pi i)^{|\boldsymbol{\alpha}|} \frac{\boldsymbol{\xi}^{\boldsymbol{\alpha}}}{|\boldsymbol{\xi}|^{l} + |\boldsymbol{\xi}|^{m}} \mathbf{A}^{\boldsymbol{\alpha}}(\mathbf{x}).$$

### Localisation principle - final generalisation

**Theorem.** Take  $\varepsilon_n > 0$  bounded,  $u_n \rightarrow 0$  in  $L^2_{loc}(\Omega; \mathbf{C}^r)$  and

$$\sum_{l \leqslant |\boldsymbol{\alpha}| \leqslant m} \varepsilon_n^{|\boldsymbol{\alpha}| - l} \partial_{\boldsymbol{\alpha}} (\mathbf{A}_n^{\boldsymbol{\alpha}} \mathbf{u}_n) = \mathbf{f}_n \,,$$

where  $\mathbf{A}_{n}^{\boldsymbol{\alpha}} \in C(\Omega; M_{r}(\mathbf{C}))$ ,  $\mathbf{A}_{n}^{\boldsymbol{\alpha}} \longrightarrow \mathbf{A}^{\boldsymbol{\alpha}}$  uniformly on compact sets, and  $f_{n} \in H_{loc}^{-m}(\Omega; \mathbf{C}^{r})$  satisfies  $(C(\varepsilon_{n}))$ .

Then for  $\omega_n \to 0^+$  such that  $c := \lim_n \frac{\varepsilon_n}{\omega_n} \in [0, \infty]$ , the corresponding one-scale H-measure  $\mu_{K_{0,\infty}}$  with characteristic length  $(\omega_n)$  satisfies

$$\mathbf{p} \boldsymbol{\mu}_{\mathrm{K}_{0,\infty}}^{ op} = \mathbf{0}$$

where

$$\mathbf{p}(\mathbf{x},\boldsymbol{\xi}) := \begin{cases} \sum_{|\boldsymbol{\alpha}|=l} \frac{\boldsymbol{\xi}^{\boldsymbol{\alpha}}}{|\boldsymbol{\xi}|^{l} + |\boldsymbol{\xi}|^{m}} \mathbf{A}^{\boldsymbol{\alpha}}(\mathbf{x}) &, \quad c = 0\\ \sum_{l \leq |\boldsymbol{\alpha}| \leq m} (2\pi i c)^{|\boldsymbol{\alpha}|} \frac{\boldsymbol{\xi}^{\boldsymbol{\alpha}}}{|\boldsymbol{\xi}|^{l} + |\boldsymbol{\xi}|^{m}} \mathbf{A}^{\boldsymbol{\alpha}}(\mathbf{x}) &, \quad c \in \langle 0, \infty \rangle\\ \sum_{|\boldsymbol{\alpha}|=m} \frac{\boldsymbol{\xi}^{\boldsymbol{\alpha}}}{|\boldsymbol{\xi}|^{l} + |\boldsymbol{\xi}|^{m}} \mathbf{A}^{\boldsymbol{\alpha}}(\mathbf{x}) &, \quad c = \infty \end{cases}$$

Moreover, if there exists  $\varepsilon_0 > 0$  such that  $\varepsilon_n > \varepsilon_0$ ,  $n \in \mathbf{N}$ , we can take

$$\mathbf{p}(\mathbf{x}, \boldsymbol{\xi}) := \sum_{|\boldsymbol{lpha}|=m} rac{\boldsymbol{\xi}^{\boldsymbol{lpha}}}{|\boldsymbol{\xi}|^m} \mathbf{A}^{\boldsymbol{lpha}}(\mathbf{x}) \,.$$

### Localisation principle - final generalisation

**Theorem.** Take  $\varepsilon_n > 0$  bounded,  $u_n \rightharpoonup 0$  in  $L^2_{loc}(\Omega; \mathbf{C}^r)$  and

$$\sum_{l \leqslant |\boldsymbol{\alpha}| \leqslant m} \varepsilon_n^{|\boldsymbol{\alpha}| - l} \partial_{\boldsymbol{\alpha}} (\mathbf{A}_n^{\boldsymbol{\alpha}} \mathbf{u}_n) = \mathbf{f}_n \,,$$

where  $\mathbf{A}_{n}^{\boldsymbol{\alpha}} \in C(\Omega; M_{r}(\mathbf{C}))$ ,  $\mathbf{A}_{n}^{\boldsymbol{\alpha}} \longrightarrow \mathbf{A}^{\boldsymbol{\alpha}}$  uniformly on compact sets, and  $f_{n} \in H_{loc}^{-m}(\Omega; \mathbf{C}^{r})$  satisfies  $(C(\varepsilon_{n}))$ .

Then for  $\omega_n \to 0^+$  such that  $c := \lim_n \frac{\varepsilon_n}{\omega_n} \in [0, \infty]$ , the corresponding one-scale H-measure  $\mu_{K_{0,\infty}}$  with characteristic length  $(\omega_n)$  satisfies

$$\mathbf{p} \boldsymbol{\mu}_{\mathrm{K}_{0,\infty}}^{ op} = \mathbf{0}$$

where

$$\mathbf{p}(\mathbf{x},\boldsymbol{\xi}) := \begin{cases} \sum_{|\boldsymbol{\alpha}|=l} \frac{\boldsymbol{\xi}^{\boldsymbol{\alpha}}}{|\boldsymbol{\xi}|^{l} + |\boldsymbol{\xi}|^{m}} \mathbf{A}^{\boldsymbol{\alpha}}(\mathbf{x}) &, \quad c = 0\\ \sum_{l \leq |\boldsymbol{\alpha}| \leq m} (2\pi i c)^{|\boldsymbol{\alpha}|} \frac{\boldsymbol{\xi}^{\boldsymbol{\alpha}}}{|\boldsymbol{\xi}|^{l} + |\boldsymbol{\xi}|^{m}} \mathbf{A}^{\boldsymbol{\alpha}}(\mathbf{x}) &, \quad c \in \langle 0, \infty \rangle\\ \sum_{|\boldsymbol{\alpha}|=m} \frac{\boldsymbol{\xi}^{\boldsymbol{\alpha}}}{|\boldsymbol{\xi}|^{l} + |\boldsymbol{\xi}|^{m}} \mathbf{A}^{\boldsymbol{\alpha}}(\mathbf{x}) &, \quad c = \infty \end{cases}$$

Moreover, if there exists  $\varepsilon_0 > 0$  such that  $\varepsilon_n > \varepsilon_0$ ,  $n \in \mathbf{N}$ , we can take

$$\mathbf{p}(\mathbf{x}, \boldsymbol{\xi}) := \sum_{|\boldsymbol{lpha}|=m} rac{\boldsymbol{\xi}^{\boldsymbol{lpha}}}{|\boldsymbol{\xi}|^m} \mathbf{A}^{\boldsymbol{lpha}}(\mathbf{x}) \,.$$

As a corollary from the previous theorem we can derive localisation principles for H-measures and semiclassical measures.

Thank you for your attention.