



Fully nonlinear mean field games

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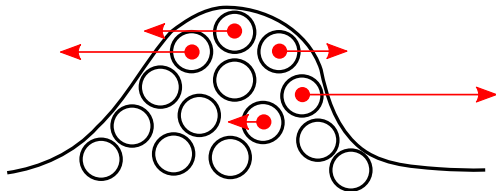
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“Classical” mean field games

$$\begin{cases} -\partial_t u = \Delta u + H(\nabla u) + f(m) & \text{on } [0, T] \times \mathbb{R}^d, \\ u(T) = g(m(T)) & \text{on } \mathbb{R}^d, \\ \partial_t m = \Delta m + \operatorname{div}(H'(\nabla u) m) & \text{on } [0, T] \times \mathbb{R}^d, \\ m(0) = m_0 & \text{on } \mathbb{R}^d. \end{cases}$$

- Agents control (individually, but interchangeably) **the drift** of a Wiener process describing their positions.





Fully nonlinear (parabolic, local/nonlocal) MFG

$$\begin{cases} -\partial_t u = F(\mathcal{L}u) + f(m) & \text{on } [0, T] \times \mathbb{R}^d, \\ u(T) = g(m(T)) & \text{on } \mathbb{R}^d, \\ \partial_t m = \mathcal{L}^*(F'(\mathcal{L}u) m) & \text{on } [0, T] \times \mathbb{R}^d, \\ m(0) = m_0 & \text{on } \mathbb{R}^d. \end{cases}$$

- Agents control **the time rate** θ of any Lévy process (\mathcal{L})
- θ is a stochastic process such that $\theta(t)$ is a stopping time
- “Local-in-time generator” $\theta'(t)\mathcal{L}$ — not Lévy, but Markov (inhomog.)
- Same for any number of Lévy processes
- To get the classical model: $\Delta, dx_1, \dots, dx_d, -dx_1, \dots, -dx_d$



Lévy operators

- Lévy \Leftrightarrow maximum principle \Leftrightarrow pseudodifferential with symbol

$$p(\xi) = ic \cdot \xi + \langle A\xi, \xi \rangle + \int_{\mathbb{R}^d \setminus \{0\}} \left(e^{iz \cdot \xi} - 1 + \mathbb{1}_{B_1}(iz \cdot \xi) \right) \nu(dz),$$
$$\int_{\mathbb{R}^d} (1 \wedge |z|^2) \nu(dz) < \infty, \quad \nu(\{0\}) = 0.$$

- Example: fractional Laplacian $\nu(dz) = \frac{1}{|z|^{d+2\sigma}} dz$, $\sigma \in (0, 1)$, $p(\xi) = |\xi|^{2\sigma}$
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- Order $2\sigma \Rightarrow \mathcal{L} : C^{2\sigma+\alpha} \rightarrow C^\alpha$
- 1) Non-degenerate $\Leftrightarrow \nu \asymp |x|^{-d-2\sigma} dz$
- 2) Degenerate $\Leftrightarrow \nu \leq |x|^{-d-2\sigma} dz$ (or analogue if ν has a singular part)



MFG – uniqueness

- Take (m_1, u_1) , (m_2, u_2) and “test” m 's against u 's
(put $m = m_1 - m_2$, $u = u_1 - u_2$, $m[\phi] = \int_{\mathbb{R}^d} \phi dm$):

$$\begin{aligned} & m(T)[u(T)] - m(0)[u(0)] \\ &= \int_0^T \left(m_1[\partial_t u + F'(\mathcal{L}u_1)\mathcal{L}u] - m_2[\partial_t u + F'(\mathcal{L}u_2)\mathcal{L}u] \right)(\tau) d\tau = \dots = 0 \end{aligned}$$

- F —convex, non-decreasing, $C^{1+\gamma}(\mathbb{R})$, f, g — monotone
- Then

$$m_1 = \mathcal{L}^*(b m_1) \text{ and } m_2 = \mathcal{L}^*(b m_2), \quad m_1(0) = m_2(0) = m_0,$$

where

$$b(t, x) = \begin{cases} \frac{F(\mathcal{L}u_1(t, x)) - F(\mathcal{L}u_2(t, x))}{\mathcal{L}u_1(t, x) - \mathcal{L}u_2(t, x)}, & \text{if } \mathcal{L}u_1(t, x) \neq \mathcal{L}u_2(t, x), \\ F'(\mathcal{L}u_1(t, x)), & \text{if } \mathcal{L}u_1(t, x) = \mathcal{L}u_2(t, x) \end{cases}$$

- We need: uniqueness of FPK, regularity of HJB.



Fokker–Planck–Kolmogorov

$$\begin{cases} \partial_t m = \mathcal{L}^*(bm) & \text{on } [0, T] \times \mathbb{R}^d, \\ m(0) = m_0 & \text{on } \mathbb{R}^d. \end{cases} \quad (\text{FPK})$$

$$b = F'(\mathcal{L}u) \quad \text{or} \quad b = \int_0^1 F'(s\mathcal{L}u_1 + (1-s)\mathcal{L}u_2) ds \quad (\text{previous slide})$$

- $b \in C([0, T] \times \mathbb{R}^d)$ and $b \geq 0$
- Natural space to look for solutions: $m \in C([0, T], \mathcal{P}(\mathbb{R}^d))$:

$$m(t)[\phi(t)] = m_0[\phi(0)] + \int_0^t m(\tau)[\partial_t \phi(\tau) + b(\tau)(\mathcal{L}\phi)(\tau)] d\tau.$$

- Existence: “easy” – set of solutions is convex, **compact** and non-empty.
- Uniqueness by Holmgren: existence of classical solutions to the dual equation

$$\partial_t w = -b \mathcal{L}w, \quad w(t) = \psi \in C_c^\infty(\mathbb{R}^d)$$

- **Non-deg**: $b \in C^\alpha$, $b \geq \kappa > 0$, Mikulevičius & Pragarauskas PotAn14
- **Deg**: $b \in C^\alpha$, $b \geq 0$, \mathcal{L} of order at most $2\sigma < \frac{7-\sqrt{33}}{4}$
- If $b_n \rightarrow b$ locally uniformly, then $\mathcal{M}_n \rightarrow \mathcal{M}$ as closed sets (“ K – lim sup”)



Hamilton–Jacobi–Bellman

$$\begin{cases} -\partial_t u = F(\mathcal{L}u) + f(t, x) & \text{on } [0, T] \times \mathbb{R}^d, \\ u(T, x) = g(x) & \text{on } \mathbb{R}^d. \end{cases} \quad (\text{HJB})$$

$$f = \mathfrak{f}(m), \quad g = \mathfrak{g}(m(T))$$

- Fully nonlinear equation \rightarrow viscosity solutions.
- Comparison principle (VS uniquely exist): Chasseigne & Jakobsen JDE17
- But we need classical solutions and **a bit more**
- **Deg**: for $2\sigma < 1$ the comparison principle is enough; no regularization

$$f, g \in C^{2\sigma+\alpha} \Rightarrow \partial_t u, \mathcal{L}u \in C^\alpha$$

- **Non-deg, local**: Schauder–Caccioppoli estimates (interior regularity)

$$f \in C^{\alpha/2, \alpha}(\mathbb{R}^d) \Rightarrow \partial_t u, D^2 u \in C^\alpha(B_1) \quad (\text{Wang CPAM92})$$

- **Non-deg, non-local**: **Conjecture**: Schauder estimates as above.
- (we end up assuming $f \in C^{1, \alpha}$ to get global boundedness, but this is bad)



MFG – existence

- We use Kakutani–Glicksberg–Fan fixed point theorem (i.e. Schauder, but for set-valued maps; solutions to FPK are **compact, convex, non-empty sets**)
- Take $\mu \in C([0, T], \mathcal{P}(\mathbb{R}^d))$, solve HJB: $\mathcal{K}_1(\mu) = u$.
- Take u and solve FPK: $\mathcal{K}_2(u) = m$
- Look for a fixed point of $\mathcal{K}(\mu) = \mathcal{K}_2(\mathcal{K}_1(\mu))$.
- Compactness of the map is easy (Prohorov theorem)
- For semi-continuity:

$$\begin{array}{ccccccccc} \mu_n & \xrightarrow{\mathcal{K}_1} & \mathfrak{f}(\mu_n), \mathfrak{g}(\mu_n) & \longmapsto & \mathcal{L}u_n & \longmapsto & b_n = F'(\mathcal{L}u_n) & \xrightarrow{\mathcal{K}_2} & \mathcal{M}_n \\ \downarrow \text{weak} & & \downarrow \text{uniform} & & \downarrow \text{loc unif} & & \downarrow \text{loc unif} & & \downarrow K\text{-lim sup} \\ \mu & \xrightarrow{\mathcal{K}_1} & \mathfrak{f}(\mu), \mathfrak{g}(\mu) & \longmapsto & \mathcal{L}u & \longmapsto & b = F'(\mathcal{L}u) & \xrightarrow{\mathcal{K}_2} & \mathcal{M} \end{array}$$



Thank you!



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