

Homogenisation of nonlocal linear elliptic operators

Marko Erceg

Department of Mathematics, Faculty of Science, University of Zagreb

7th Croatian Mathematical Congress

Split, 15th June 2022

Joint work with K. Burazin and M. Krupski

IP-2018-01-2449 (MiTPDE)



- Passage from micro-scale to macro-scale
- Deriving lower-dimensional models
- Averaging highly heterogeneous materials

Homogenisation - mathematical approach

$\Omega \subseteq \mathbb{R}^d$ open and bounded.

$$\begin{cases} -\operatorname{div}(\mathbf{A}_n \nabla u_n) = f & \text{in } \Omega \\ u_n = 0 & \text{on } \partial\Omega \end{cases}$$

Homogenisation - mathematical approach

$\Omega \subseteq \mathbb{R}^d$ open and bounded.

$$\begin{cases} -\operatorname{div}(\mathbf{A}_n \nabla u_n) = f & \text{in } \Omega \\ u_n \in H_0^1(\Omega) \end{cases}$$

- $f \in H^{-1}(\Omega)$
- $\mathbf{A}_n \in \mathcal{M}(\alpha, \beta)$, i.e. $\mathbf{A}_n \in L^\infty(\Omega; \mathbb{R}^{d \times d})$

$$\mathbf{A}_n(\mathbf{x}) \boldsymbol{\xi} \cdot \boldsymbol{\xi} \geq \alpha |\boldsymbol{\xi}|^2$$

$$\mathbf{A}_n(\mathbf{x}) \boldsymbol{\xi} \cdot \boldsymbol{\xi} \geq \frac{1}{\beta} |\mathbf{A}_n(\mathbf{x}) \boldsymbol{\xi}|^2$$

Homogenisation - mathematical approach

$\Omega \subseteq \mathbb{R}^d$ open and bounded.

$$\begin{cases} -\operatorname{div}(\mathbf{A}_n \nabla u_n) = f & \text{in } \Omega \\ u_n \in H_0^1(\Omega) \end{cases}$$

- $f \in H^{-1}(\Omega)$
- $\mathbf{A}_n \in \mathcal{M}(\alpha, \beta)$, i.e. $\mathbf{A}_n \in L^\infty(\Omega; \mathbb{R}^{d \times d})$

$$\begin{aligned} \mathbf{A}_n(\mathbf{x}) \boldsymbol{\xi} \cdot \boldsymbol{\xi} &\geq \alpha |\boldsymbol{\xi}|^2 \\ \mathbf{A}_n(\mathbf{x}) \boldsymbol{\xi} \cdot \boldsymbol{\xi} &\geq \frac{1}{\beta} |\mathbf{A}_n(\mathbf{x}) \boldsymbol{\xi}|^2 \end{aligned}$$

\implies **unique** solution $u_n \in H_0^1(\Omega)$, and (u_n) **bounded** in $H_0^1(\Omega)$

Homogenisation - mathematical approach

$\Omega \subseteq \mathbb{R}^d$ open and bounded.

$$\begin{cases} -\operatorname{div}(\mathbf{A}_n \nabla u_n) = f & \text{in } \Omega \\ u_n \in H_0^1(\Omega) \end{cases}$$

- $f \in H^{-1}(\Omega)$
- $\mathbf{A}_n \in \mathcal{M}(\alpha, \beta)$, i.e. $\mathbf{A}_n \in L^\infty(\Omega; \mathbb{R}^{d \times d})$

$$\begin{aligned} \mathbf{A}_n(\mathbf{x}) \boldsymbol{\xi} \cdot \boldsymbol{\xi} &\geq \alpha |\boldsymbol{\xi}|^2 \\ \mathbf{A}_n(\mathbf{x}) \boldsymbol{\xi} \cdot \boldsymbol{\xi} &\geq \frac{1}{\beta} |\mathbf{A}_n(\mathbf{x}) \boldsymbol{\xi}|^2 \end{aligned}$$

\implies **unique** solution $u_n \in H_0^1(\Omega)$, and (u_n) **bounded** in $H_0^1(\Omega)$

\implies (up to a subseq.) $u_n \rightharpoonup u_0$ in $H_0^1(\Omega)$

Homogenisation - mathematical approach

$\Omega \subseteq \mathbb{R}^d$ open and bounded.

$$\begin{cases} -\operatorname{div}(\mathbf{A}_n \nabla u_n) = f & \text{in } \Omega \\ u_n \in H_0^1(\Omega) \end{cases}$$

- $f \in H^{-1}(\Omega)$
- $\mathbf{A}_n \in \mathcal{M}(\alpha, \beta)$, i.e. $\mathbf{A}_n \in L^\infty(\Omega; \mathbb{R}^{d \times d})$

$$\begin{aligned} \mathbf{A}_n(\mathbf{x}) \boldsymbol{\xi} \cdot \boldsymbol{\xi} &\geq \alpha |\boldsymbol{\xi}|^2 \\ \mathbf{A}_n(\mathbf{x}) \boldsymbol{\xi} \cdot \boldsymbol{\xi} &\geq \frac{1}{\beta} |\mathbf{A}_n(\mathbf{x}) \boldsymbol{\xi}|^2 \end{aligned}$$

\implies **unique** solution $u_n \in H_0^1(\Omega)$, and (u_n) **bounded** in $H_0^1(\Omega)$

\implies (up to a subseq.) $u_n \rightharpoonup u_0$ in $H_0^1(\Omega)$

Question: Which equation u_0 satisfies?

$$\begin{cases} -\operatorname{div}(\mathbf{A}_n \nabla u_n) = f & \text{in } \Omega \\ u_n \in H_0^1(\Omega) \end{cases}$$

Various methods:

- G -convergence
- H -convergence
- Asymptotic expansion
- Two-scale convergence
- Γ -convergence

Some books:

Allaire G., Shape Optimization by the Homogenization Method (2002)

Tartar L., The General Theory of Homogenization (2009)

Chechkin G. A., Piatnitski A. L., Shamaev A. S., Homogenization. Methods and applications (2007)

$$\begin{cases} -\operatorname{div}(\mathbf{A}_n \nabla u_n) = f & \text{in } \Omega \\ u_n \in H_0^1(\Omega) \end{cases}$$

Various methods:

- G -convergence
- H -convergence
- Asymptotic expansion
- Two-scale convergence
- Γ -convergence

Some books:

Allaire G., Shape Optimization by the Homogenization Method (2002)

Tartar L., The General Theory of Homogenization (2009)

Chechkin G. A., Piatnitski A. L., Shamaev A. S., Homogenization. Methods and applications (2007)

$$\begin{cases} -\operatorname{div}(\mathbf{A}_n \nabla u_n) = f & \text{in } \Omega \\ u_n \in H_0^1(\Omega) \end{cases}$$

$\mathcal{M}(\alpha, \beta) \ni \mathbf{A}_n \xrightarrow{H} \mathbf{A}_0 \in \mathcal{M}(\alpha', \beta')$ iff for any $f \in H^{-1}(\Omega)$

$$\begin{aligned} u_n &\rightharpoonup u_0 & \text{in } H_0^1(\Omega) \\ \mathbf{A}_n \nabla u_n &\rightharpoonup \mathbf{A}_0 \nabla u_0 & \text{in } L^2(\Omega; \mathbb{R}^d), \end{aligned}$$

where u_0 solves the problem for \mathbf{A}_0 .

$$\begin{cases} -\operatorname{div}(\mathbf{A}_n \nabla u_n) = f & \text{in } \Omega \\ u_n \in H_0^1(\Omega) \end{cases}$$

$\mathcal{M}(\alpha, \beta) \ni \mathbf{A}_n \xrightarrow{H} \mathbf{A}_0 \in \mathcal{M}(\alpha', \beta')$ iff for any $f \in H^{-1}(\Omega)$

$$\begin{aligned} u_n &\rightharpoonup u_0 && \text{in } H_0^1(\Omega) \\ \mathbf{A}_n \nabla u_n &\rightharpoonup \mathbf{A}_0 \nabla u_0 && \text{in } L^2(\Omega; \mathbb{R}^d), \end{aligned}$$

where u_0 solves the problem for \mathbf{A}_0 .

H-compactness:

There exists $\mathbf{A}_0 \in \mathcal{M}(\alpha, \beta)$ such that (up to a subseq.) $\mathbf{A}_n \xrightarrow{H} \mathbf{A}_0$.

Lower order terms - correctors

$$\begin{cases} -\operatorname{div}(\mathbf{A}_n \nabla u_n) + \mathbf{b}_n \cdot \nabla u_n = f & \text{in } \Omega \\ u_n \in H_0^1(\Omega) \end{cases}$$

$\mathbf{A}_n \xrightarrow{H} \mathbf{A}_0$, \mathbf{b}_n bounded in $L^p(\Omega; \mathbb{R}^d)$, $p > d$, $u_n \rightharpoonup u_0$ in $H_{loc}^1(\Omega)$.

$$\begin{cases} -\operatorname{div}(\mathbf{A}_n \nabla u_n) + \mathbf{b}_n \cdot \nabla u_n = f & \text{in } \Omega \\ u_n \in H_0^1(\Omega) \end{cases}$$

$\mathbf{A}_n \xrightarrow{H} \mathbf{A}_0$, \mathbf{b}_n bounded in $L^p(\Omega; \mathbb{R}^d)$, $p > d$, $u_n \rightharpoonup u_0$ in $H_{loc}^1(\Omega)$.

Existence of correctors:

If $\mathbf{A}_n \xrightarrow{H} \mathbf{A}_0$, then there exists $P_n \in L^2(\Omega; \mathbb{R}^{d \times d})$ such that

$$\nabla u_n - P_n \nabla u_0 \rightarrow 0 \quad \text{in } L_{loc}^1(\Omega; \mathbb{R}^d).$$

$$\begin{cases} -\operatorname{div}(\mathbf{A}_n \nabla u_n) + \mathbf{b}_n \cdot \nabla u_n = f & \text{in } \Omega \\ u_n \in H_0^1(\Omega) \end{cases}$$

$\mathbf{A}_n \xrightarrow{H} \mathbf{A}_0$, \mathbf{b}_n bounded in $L^p(\Omega; \mathbb{R}^d)$, $p > d$, $u_n \rightharpoonup u_0$ in $H_{loc}^1(\Omega)$.

Existence of correctors:

If $\mathbf{A}_n \xrightarrow{H} \mathbf{A}_0$, then there exists $P_n \in L^2(\Omega; \mathbb{R}^{d \times d})$ such that

$$\nabla u_n - P_n \nabla u_0 \rightarrow 0 \quad \text{in } L_{loc}^1(\Omega; \mathbb{R}^d).$$

Application of correctors:

Rewrite the equation as

$$\begin{aligned} -\operatorname{div}(\mathbf{A}_n \nabla u_n) + P_n^T \mathbf{b}_n \cdot \nabla u_0 &= f - \mathbf{b}_n \cdot (\nabla u_n - P_n \nabla u_0) \\ &\quad \downarrow n \rightarrow \infty \\ -\operatorname{div}(\mathbf{A}_0 \nabla u_0) + \mathbf{b}_0 \cdot \nabla u_0 &= f - 0 \end{aligned}$$

Fractional Sobolev spaces 1/2

$$s \in (0, 1)$$

$u \in H^s(\mathbb{R}^d)$ iff $u \in L^2(\mathbb{R}^d)$ and

$$(D_s u)(\mathbf{x}, \mathbf{y}) := \frac{u(\mathbf{x}) - u(\mathbf{y})}{|\mathbf{x} - \mathbf{y}|^{d/2+s}} \in L^2(\mathbb{R}^d \times \mathbb{R}^d).$$

E.g. $H^1(\mathbb{R}^d) \subseteq H^s(\mathbb{R}^d)$.

$H^s(\mathbb{R}^d)$ equipped with

$$\|u\|_s := \sqrt{\|u\|_{L^2(\mathbb{R}^d)}^2 + \|D_s u\|_{L^2(\mathbb{R}^{2d})}^2}$$

is a Hilbert space.

For $\Omega \subseteq \mathbb{R}^d$ open and bounded with a smooth boundary we define $H_0^s(\Omega)$ as the completion of $C_c^\infty(\Omega)$ in $H^s(\mathbb{R}^d)$.

It holds:

$$H_0^s(\Omega) = \{u \in H^s(\mathbb{R}^d) : u = 0 \text{ a.e. in } \mathbb{R}^d \setminus \Omega\}.$$

Poincaré inequality: $\exists C > 0$ s.t.

$$\|u\|_{L^2(\mathbb{R}^d)} \leq C \|D_s u\|_{L^2(\mathbb{R}^d \times \mathbb{R}^d)}, \quad u \in H_0^s(\mathbb{R}^d).$$

Compact embeddings:

For (u_n) bounded in $H_0^s(\Omega)$ there exists a subsequence $(u_{n'})$ and $u_0 \in H_0^s(\Omega)$ such that $u_{n'} \rightarrow u_0$ in $L^2(\mathbb{R}^d)$.

Non-local elliptic operators - symmetric case

$$\mathcal{L}_a u(x) := \text{p.v.} \int_{\mathbb{R}^d} a(\mathbf{x}, \mathbf{y}) \frac{u(\mathbf{x}) - u(\mathbf{y})}{|\mathbf{x} - \mathbf{y}|^{d+2s}} d\mathbf{y}, \quad s \in (0, 1)$$

Motivation:

- Modelling: diffusion with long range interactions
- Probability: infinitesimal generator of stable Lévy processes

$$\mathcal{L}_a u(x) := \text{p.v.} \int_{\mathbb{R}^d} a(\mathbf{x}, \mathbf{y}) \frac{u(\mathbf{x}) - u(\mathbf{y})}{|\mathbf{x} - \mathbf{y}|^{d+2s}} d\mathbf{y}, \quad s \in (0, 1)$$

$$a \in \mathcal{A}_{sym}(\alpha, \beta) := \{a \in L^\infty(\mathbb{R}^{2d}) : a(\mathbf{x}, \mathbf{y}) \in [\alpha, \beta] \text{ for a.e. } (\mathbf{x}, \mathbf{y}) \in \mathbb{R}^{2d}\},$$

where $0 < \alpha \leq \beta < \infty$.

Non-local elliptic operators - symmetric case

$$\mathcal{L}_a u(x) := \text{p.v.} \int_{\mathbb{R}^d} a(\mathbf{x}, \mathbf{y}) \frac{u(\mathbf{x}) - u(\mathbf{y})}{|\mathbf{x} - \mathbf{y}|^{d+2s}} d\mathbf{y}, \quad s \in (0, 1)$$

$$a \in \mathcal{A}_{sym}(\alpha, \beta) := \{a \in L^\infty(\mathbb{R}^{2d}) : a(\mathbf{x}, \mathbf{y}) \in [\alpha, \beta] \text{ for a.e. } (\mathbf{x}, \mathbf{y}) \in \mathbb{R}^{2d}\},$$

where $0 < \alpha \leq \beta < \infty$.

$$\begin{aligned} \langle \mathcal{L}_a u, v \rangle &= \iint_{\mathbb{R}^{2d}} a(\mathbf{x}, \mathbf{y}) \frac{u(\mathbf{x}) - u(\mathbf{y})}{|\mathbf{x} - \mathbf{y}|^{d+2s}} v(\mathbf{x}) d\mathbf{y} d\mathbf{x} \\ &= \iint_{\mathbb{R}^{2d}} a(\mathbf{y}, \mathbf{x}) \frac{u(\mathbf{y}) - u(\mathbf{x})}{|\mathbf{y} - \mathbf{x}|^{d+2s}} v(\mathbf{y}) d\mathbf{x} d\mathbf{y} \\ \implies \langle \mathcal{L}_a u, v \rangle &= \frac{1}{2} \iint_{\mathbb{R}^{2d}} a(\mathbf{x}, \mathbf{y}) \frac{u(\mathbf{x}) - u(\mathbf{y})}{|\mathbf{x} - \mathbf{y}|^{d+2s}} (v(\mathbf{x}) - v(\mathbf{y})) d\mathbf{y} d\mathbf{x} \\ &= \frac{1}{2} \langle a D_s u, D_s v \rangle \end{aligned}$$

$$\mathcal{L}_a u(x) := \text{p.v.} \int_{\mathbb{R}^d} a(\mathbf{x}, \mathbf{y}) \frac{u(\mathbf{x}) - u(\mathbf{y})}{|\mathbf{x} - \mathbf{y}|^{d+2s}} d\mathbf{y}, \quad s \in (0, 1)$$

$$a \in \mathcal{A}_{sym}(\alpha, \beta) := \{a \in L^\infty(\mathbb{R}^{2d}) : a(\mathbf{x}, \mathbf{y}) \in [\alpha, \beta] \text{ for a.e. } (\mathbf{x}, \mathbf{y}) \in \mathbb{R}^{2d}\},$$

where $0 < \alpha \leq \beta < \infty$.

$$\langle \mathcal{L}_a u, v \rangle = \frac{1}{2} \langle a D_s u, D_s v \rangle, \quad u, v \in H_0^s(\Omega).$$

Non-local elliptic operators - symmetric case

$$\mathcal{L}_a u(x) := \text{p.v.} \int_{\mathbb{R}^d} a(\mathbf{x}, \mathbf{y}) \frac{u(\mathbf{x}) - u(\mathbf{y})}{|\mathbf{x} - \mathbf{y}|^{d+2s}} d\mathbf{y}, \quad s \in (0, 1)$$

$$a \in \mathcal{A}_{sym}(\alpha, \beta) := \{a \in L^\infty(\mathbb{R}^{2d}) : a(\mathbf{x}, \mathbf{y}) \in [\alpha, \beta] \text{ for a.e. } (\mathbf{x}, \mathbf{y}) \in \mathbb{R}^{2d}\},$$

where $0 < \alpha \leq \beta < \infty$.

$$\langle \mathcal{L}_a u, v \rangle = \frac{1}{2} \langle a D_s u, D_s v \rangle, \quad u, v \in H_0^s(\Omega).$$

Thus, \mathcal{L}_a bounded and coercive \implies **well-posedness** of
($f \in H^{-1}(\Omega) := (H_0^s(\Omega))'$)

$$\begin{cases} \mathcal{L}_a u = f \\ u \in H_0^s(\Omega) \end{cases}.$$

Non-local div-rot lemma

Recall,

$$(D_s u)(\mathbf{x}, \mathbf{y}) := \frac{u(\mathbf{x}) - u(\mathbf{y})}{|\mathbf{x} - \mathbf{y}|^{d/2+s}}, \quad u \in H_0^s(\Omega).$$

Define **non-local divergence** as

$$(d_s \phi)(\mathbf{x}) := \text{p.v.} \int_{\mathbb{R}^d} \frac{\phi(\mathbf{x}, \mathbf{y}) - \phi(\mathbf{y}, \mathbf{x})}{|\mathbf{x} - \mathbf{y}|^{d/2+s}} d\mathbf{y}, \quad \phi \in L^2(\mathbb{R}^d \times \mathbb{R}^d).$$

Non-local div-rot lemma

Recall,

$$(D_s u)(\mathbf{x}, \mathbf{y}) := \frac{u(\mathbf{x}) - u(\mathbf{y})}{|\mathbf{x} - \mathbf{y}|^{d/2+s}}, \quad u \in H_0^s(\Omega).$$

Define **non-local divergence** as

$$(d_s \phi)(\mathbf{x}) := \text{p.v.} \int_{\mathbb{R}^d} \frac{\phi(\mathbf{x}, \mathbf{y}) - \phi(\mathbf{y}, \mathbf{x})}{|\mathbf{x} - \mathbf{y}|^{d/2+s}} d\mathbf{y} \in H^{-s}(\Omega), \quad \phi \in L^2(\mathbb{R}^d \times \mathbb{R}^d).$$

$$\langle \phi, D_s u \rangle = \langle d_s \phi, u \rangle$$

Non-local div-rot lemma

Recall,

$$(D_s u)(\mathbf{x}, \mathbf{y}) := \frac{u(\mathbf{x}) - u(\mathbf{y})}{|\mathbf{x} - \mathbf{y}|^{d/2+s}}, \quad u \in H_0^s(\Omega).$$

Define **non-local divergence** as

$$(d_s \phi)(\mathbf{x}) := \text{p.v.} \int_{\mathbb{R}^d} \frac{\phi(\mathbf{x}, \mathbf{y}) - \phi(\mathbf{y}, \mathbf{x})}{|\mathbf{x} - \mathbf{y}|^{d/2+s}} d\mathbf{y} \in H^{-s}(\Omega), \quad \phi \in L^2(\mathbb{R}^d \times \mathbb{R}^d).$$

$$\langle \phi, D_s u \rangle = \langle d_s \phi, u \rangle$$

$$\langle \mathcal{L}_a u, v \rangle = \frac{1}{2} \langle a D_s u, D_s v \rangle \implies \mathcal{L}_a u = \frac{1}{2} d_s(a D_s u)$$

Non-local div-rot lemma

Recall,

$$(D_s u)(\mathbf{x}, \mathbf{y}) := \frac{u(\mathbf{x}) - u(\mathbf{y})}{|\mathbf{x} - \mathbf{y}|^{d/2+s}}, \quad u \in H_0^s(\Omega).$$

Define **non-local divergence** as

$$(d_s \phi)(\mathbf{x}) := \text{p.v.} \int_{\mathbb{R}^d} \frac{\phi(\mathbf{x}, \mathbf{y}) - \phi(\mathbf{y}, \mathbf{x})}{|\mathbf{x} - \mathbf{y}|^{d/2+s}} d\mathbf{y} \in H^{-s}(\Omega), \quad \phi \in L^2(\mathbb{R}^d \times \mathbb{R}^d).$$

Lemma (Bonder, Ritorto, Salort, SIAM J. Math. Anal. (2017))

$$\begin{cases} v_n \rightharpoonup v_0 & \text{in } H^s(\mathbb{R}^d) \\ \phi_n \rightharpoonup \phi_0 & \text{in } L^2(\mathbb{R}^{2d}) \\ d_s \phi_n \rightarrow d_s \phi & \text{in } H_{loc}^{-s}(\mathbb{R}^d) \end{cases}$$

$$\implies \phi_n D_s v_n \rightarrow \phi_0 D_s v_0 \text{ in } \mathcal{D}'(\mathbb{R}^{2d}).$$

Non-local problem - H-convergence

$$\begin{cases} \mathcal{L}_{a_n} u_n = f \\ u_n \in H_0^s(\Omega) \end{cases} .$$

$\mathcal{A}(\alpha, \beta) \ni a_n \xrightarrow{H} a_0 \in \mathcal{A}(\alpha, \beta)$ iff for any $f \in H^{-s}(\Omega)$

$$\begin{aligned} u_n &\rightharpoonup u_0 \quad \text{in } H_0^s(\Omega) \\ a_n D_s u_n &\rightharpoonup a_0 D_s u_0 \quad \text{in } L^2(\mathbb{R}^{2d}) , \end{aligned}$$

where u_0 solves the problem for a_0 .

Non-local problem - H-convergence

$$\begin{cases} \mathcal{L}_{a_n} u_n = f \\ u_n \in H_0^s(\Omega) \end{cases} .$$

$\mathcal{A}(\alpha, \beta) \ni a_n \xrightarrow{H} a_0 \in \mathcal{A}(\alpha, \beta)$ iff for any $f \in H^{-s}(\Omega)$

$$\begin{aligned} u_n &\rightharpoonup u_0 \quad \text{in } H_0^s(\Omega) \\ a_n D_s u_n &\rightharpoonup a_0 D_s u_0 \quad \text{in } L^2(\mathbb{R}^{2d}), \end{aligned}$$

where u_0 solves the problem for a_0 .

H-compactness: (Bonder et al. (2017))

There exists $a_0 \in \mathcal{A}(\alpha, \beta')$ such that (up to a subseq.) $a_n \xrightarrow{H} a_0$.

Non-local problem - H-convergence

$$\begin{cases} \mathcal{L}_{a_n} u_n = f \\ u_n \in H_0^s(\Omega) \end{cases} .$$

$\mathcal{A}(\alpha, \beta) \ni a_n \xrightarrow{H} a_0 \in \mathcal{A}(\alpha, \beta)$ iff for any $f \in H^{-s}(\Omega)$

$$\begin{aligned} u_n &\rightharpoonup u_0 \quad \text{in } H_0^s(\Omega) \\ a_n D_s u_n &\rightharpoonup a_0 D_s u_0 \quad \text{in } L^2(\mathbb{R}^{2d}) , \end{aligned}$$

where u_0 solves the problem for a_0 .

H-compactness: (Bonder et al. (2017))

There exists $a_0 \in \mathcal{A}(\alpha, \beta')$ such that (up to a subseq.) $a_n \xrightarrow{H} a_0$.

Characterisation: (Bellido, Evgrafov, Rev. Mat. Complut. (2021))

$a_n \xrightarrow{*} a_0$ in $L^\infty(\mathbb{R}^{2d})$ iff $a_n \xrightarrow{H} a_0$.

Non-symmetric case - well-posedness

$$a_{sym}(\mathbf{x}, \mathbf{y}) := (a(\mathbf{x}, \mathbf{y}) + a(\mathbf{y}, \mathbf{x}))/2$$

$$a_{anti}(\mathbf{x}, \mathbf{y}) := (a(\mathbf{x}, \mathbf{y}) - a(\mathbf{y}, \mathbf{x}))/2$$

$$\mathcal{L}_a = \mathcal{L}_{a_{sym}} + \mathcal{L}_{a_{anti}}$$

Sufficient conditions for well-posedness of $\mathcal{L}_a u = f$ in $H_0^s(\Omega)$:
there exist $\alpha, \beta, \gamma > 0$ s.t.

- $a(\mathbf{x}, \mathbf{y}) \in [\alpha, \beta]$ for a.e. $(\mathbf{x}, \mathbf{y}) \in \mathbb{R}^{2d}$,
- $\sup_{\mathbf{x} \in \mathbb{R}^d} \int_{\mathbb{R}^d} \frac{|a_{anti}(\mathbf{x}, \mathbf{y})|^2}{|\mathbf{x} - \mathbf{y}|^{d+2s}} d\mathbf{y} \leq \gamma$,
- $\inf_{\mathbf{x} \in \mathbb{R}^d} \limsup_{\epsilon \rightarrow 0^+} \int_{\mathbb{R}^d \setminus B_\epsilon(\mathbf{x})} \frac{a_{anti}(\mathbf{x}, \mathbf{y})}{|\mathbf{x} - \mathbf{y}|^{d+2s}} d\mathbf{y} \geq 0$.

Non-symmetric case - well-posedness

$$a_{sym}(\mathbf{x}, \mathbf{y}) := (a(\mathbf{x}, \mathbf{y}) + a(\mathbf{y}, \mathbf{x}))/2$$

$$a_{anti}(\mathbf{x}, \mathbf{y}) := (a(\mathbf{x}, \mathbf{y}) - a(\mathbf{y}, \mathbf{x}))/2$$

$$\mathcal{L}_a = \mathcal{L}_{a_{sym}} + \mathcal{L}_{a_{anti}}$$

Sufficient conditions for well-posedness of $\mathcal{L}_a u = f$ in $H_0^s(\Omega)$:
there exist $\alpha, \beta, \gamma > 0$ s.t.

- $a(\mathbf{x}, \mathbf{y}) \in [\alpha, \beta]$ for a.e. $(\mathbf{x}, \mathbf{y}) \in \mathbb{R}^{2d}$,
- $\sup_{\mathbf{x} \in \mathbb{R}^d} \int_{\mathbb{R}^d} \frac{|a_{anti}(\mathbf{x}, \mathbf{y})|^2}{|\mathbf{x} - \mathbf{y}|^{d+2s}} d\mathbf{y} \leq \gamma$, $\implies \mathcal{L}_{a_{anti}}$ bounded from $H_0^s(\Omega)$ to $L^2(\Omega)$
- $\inf_{\mathbf{x} \in \mathbb{R}^d} \limsup_{\epsilon \rightarrow 0^+} \int_{\mathbb{R}^d \setminus B_\epsilon(\mathbf{x})} \frac{a_{anti}(\mathbf{x}, \mathbf{y})}{|\mathbf{x} - \mathbf{y}|^{d+2s}} d\mathbf{y} \geq 0$.

Non-symmetric case - H-convergence

$$\begin{cases} \mathcal{L}_{a_{sym}^n} u + \mathcal{L}_{a_{anti}^n} u_n = f \\ u_n \in H_0^s(\Omega) \end{cases}$$

Homogenisation:

With the suitable theory of correctors one can pass to a limit as in the local (classical) setting.

Non-symmetric case - H-convergence

$$\begin{cases} \mathcal{L}_{a_{sym}^n} u + \mathcal{L}_{a_{anti}^n} u_n = f \\ u_n \in H_0^s(\Omega) \end{cases}$$

Homogenisation:

With the suitable theory of correctors one can pass to a limit as in the local (classical) setting.

Up to now we have results only for certain cases (work in progress!).

E.g. for $a_n(\mathbf{y}, \mathbf{y}) = b_n(\mathbf{x})c_n(\mathbf{x}, \mathbf{y})$, where $c \in \mathcal{A}(\alpha, \beta)$ and $\alpha \leq b_n \leq \beta$ we have

$$a_n \xrightarrow{H} c_0/\bar{b},$$

where $1/\bar{b}_n$ is the weak-* limit of $1/b_n$ (effect not present in the symmetric case!)

Non-symmetric case - H-convergence

$$\begin{cases} \mathcal{L}_{a_{sym}^n} u + \mathcal{L}_{a_{anti}^n} u_n = f \\ u_n \in H_0^s(\Omega) \end{cases}$$

Homogenisation:

With the suitable theory of correctors one can pass to a limit as in the local (classical) setting.

Up to now we have results only for certain cases (work in progress!).

E.g. for $a_n(\mathbf{y}, \mathbf{y}) = b_n(\mathbf{x})c_n(\mathbf{x}, \mathbf{y})$, where $c \in \mathcal{A}(\alpha, \beta)$ and $\alpha \leq b_n \leq \beta$ we have

$$a_n \xrightarrow{H} c_0/\bar{b},$$

where $1/\bar{b}_n$ is the weak-* limit of $1/b_n$ (effect not present in the symmetric case!)

Kassmann, Piatnitski, Zhizhina, SIAM J. Math. Anal. (2019): non-symmetric a , but in the periodic setting.

And...

...thank you for your attention :)