

# Compensated compactness in the $L^p$ – $L^q$ setting

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## Div-rot lemma in $L^2$

**Theorem 1.** *Assume that  $\Omega$  is open and bounded subset of  $\mathbf{R}^3$ , and that it holds:*

$$\mathbf{u}_n \rightharpoonup \mathbf{u} \text{ in } L^2(\Omega; \mathbf{R}^3),$$

$$\mathbf{v}_n \rightharpoonup \mathbf{v} \text{ in } L^2(\Omega; \mathbf{R}^3),$$

$$\text{rot } \mathbf{u}_n \text{ bounded in } L^2(\Omega; \mathbf{R}^3), \text{ div } \mathbf{v}_n \text{ bounded in } L^2(\Omega).$$

*Then*

$$\mathbf{u}_n \cdot \mathbf{v}_n \rightharpoonup \mathbf{u} \cdot \mathbf{v}$$

*in the sense of distributions.*



## Quadratic theorem

**Theorem 2. (Quadratic theorem)** Assume that  $\Omega \subseteq \mathbf{R}^d$  is open and that  $\Lambda \subseteq \mathbf{R}^r$  is defined by

$$\Lambda := \left\{ \boldsymbol{\lambda} \in \mathbf{R}^r : (\exists \boldsymbol{\xi} \in \mathbf{R}^d \setminus \{0\}) \sum_{k=1}^d \xi_k \mathbf{A}^k \boldsymbol{\lambda} = 0 \right\},$$

where  $Q$  is a real quadratic form on  $\mathbf{R}^r$ , which is nonnegative on  $\Lambda$ , i.e.

$$(\forall \boldsymbol{\lambda} \in \Lambda) \quad Q(\boldsymbol{\lambda}) \geq 0.$$

Furthermore, assume that the sequence of functions  $(\mathbf{u}_n)$  satisfies

$$\begin{aligned} \mathbf{u}_n &\rightharpoonup \mathbf{u} \quad \text{weakly in } L^2_{\text{loc}}(\Omega; \mathbf{R}^r), \\ \left( \sum_k \mathbf{A}^k \partial_k \mathbf{u}_n \right) &\text{ relatively compact in } H^{-1}_{\text{loc}}(\Omega; \mathbf{R}^q). \end{aligned}$$

Then every subsequence of  $(Q \circ \mathbf{u}_n)$  which converges in distributions to its limit  $L$ , satisfies

$$L \geq Q \circ \mathbf{u}$$

in the sense of distributions. ■

The most general version of the classical  $L^2$  results has recently been proved by E. Yu. Panov (2011):

Assume that the sequence  $(\mathbf{u}_n)$  is bounded in  $L^p(\mathbf{R}^d; \mathbf{R}^r)$ ,  $2 \leq p < \infty$ , and converges weakly in  $\mathcal{D}'(\mathbf{R}^d)$  to a vector function  $\mathbf{u}$ .

Let  $q = p'$  if  $p < \infty$ , and  $q > 1$  if  $p = \infty$ . Assume that the sequence

$$\sum_{k=1}^{\nu} \partial_k(\mathbf{A}^k \mathbf{u}_n) + \sum_{k,l=\nu+1}^d \partial_{kl}(\mathbf{B}^{kl} \mathbf{u}_n)$$

is precompact in the anisotropic Sobolev space  $W_{loc}^{-1,-2;q}(\mathbf{R}^d; \mathbf{R}^m)$ , where  $m \times r$  matrices  $\mathbf{A}^k$  and  $\mathbf{B}^{kl}$  have variable coefficients belonging to  $L^{2\bar{q}}(\mathbf{R}^d)$ ,  $\bar{q} = \frac{p}{p-2}$  if  $p > 2$ , and to the space  $C(\mathbf{R}^d)$  if  $p = 2$ .

We introduce the set  $\Lambda(\mathbf{x})$

$$\Lambda(\mathbf{x}) = \left\{ \boldsymbol{\lambda} \in \mathbf{C}^r \mid (\exists \boldsymbol{\xi} \in \mathbf{R}^d \setminus \{0\}) : \right. \quad (1)$$

$$\left. \left( i \sum_{k=1}^{\nu} \xi_k \mathbf{A}^k(\mathbf{x}) - 2\pi \sum_{k,l=\nu+1}^d \xi_k \xi_l \mathbf{B}^{kl}(\mathbf{x}) \right) \boldsymbol{\lambda} = \mathbf{0}_m \right\},$$

and consider the bilinear form on  $\mathbf{C}^r$

$$q(\mathbf{x}, \boldsymbol{\lambda}, \boldsymbol{\eta}) = \mathbf{Q}(\mathbf{x}) \boldsymbol{\lambda} \cdot \boldsymbol{\eta}, \quad (2)$$

where  $\mathbf{Q} \in L_{loc}^{\bar{q}}(\mathbf{R}^d; \text{Sym}_r)$  if  $p > 2$  and  $\mathbf{Q} \in C(\mathbf{R}^d; \text{Sym}_r)$  if  $p = 2$ .  
 Finally, let  $q(\mathbf{x}, \mathbf{u}_n, \mathbf{u}_n) \rightharpoonup \omega$  weakly in the space of distributions.

## Result by Panov

The following theorem holds

**Theorem 3.** [P, 2011] Assume that  $(\forall \boldsymbol{\lambda} \in \Lambda(\mathbf{x})) q(\mathbf{x}, \boldsymbol{\lambda}, \boldsymbol{\lambda}) \geq 0$  (a.e.  $\mathbf{x} \in \mathbf{R}^d$ ) and  $\mathbf{u}_n \rightarrow \mathbf{u}$ , then  $q(\mathbf{x}, \mathbf{u}(\mathbf{x}), \mathbf{u}(\mathbf{x})) \leq \omega$ . ■

The connection between  $q$  and  $\Lambda$  given in the previous theorem, we shall call *the consistency condition*.

## H-distributions

H-distributions were introduced by N. Antonić and D. Mitrović (2011) as an extension of H-measures to the  $L^p - L^q$  context.

M. Lazar and D. Mitrović (2012) extended and applied them on a velocity averaging problem.

We need Fourier multiplier operators with symbols defined on a manifold  $P$  determined by  $d$ -tuple  $\alpha \in (\mathbf{R}^+)^d$ :

$$P = \left\{ \boldsymbol{\xi} \in \mathbf{R}^d : \sum_{k=1}^d |\xi_k|^{2\alpha_k} = 1 \right\},$$

where  $\alpha_k \in \mathbf{N}$  or  $\alpha_k \geq d$ . In order to associate an  $L^p$  Fourier multiplier to a function defined on  $P$ , we extend it to  $\mathbf{R}^d \setminus \{0\}$  by means of the projection

$$(\pi_P(\boldsymbol{\xi}))_j = \xi_j \left( |\xi_1|^{2\alpha_1} + \dots + |\xi_d|^{2\alpha_d} \right)^{-1/2\alpha_j}, \quad j = 1, \dots, d.$$

We need the following extension of the results given above.

**Theorem 4.** *Let  $(u_n)$  be a bounded sequence in  $L^p(\mathbf{R}^d)$ ,  $p > 1$ , and let  $(v_n)$  be a bounded sequence of uniformly compactly supported functions in  $L^q(\mathbf{R}^d)$ ,  $1/q + 1/p < 1$ . Then, after passing to a subsequence (not relabelled), for any  $\bar{s} \in (1, \frac{pq}{p+q})$  there exists a continuous bilinear functional  $B$  on  $L^{\bar{s}'}(\mathbf{R}^d) \otimes C^d(P)$  such that for every  $\varphi \in L^{\bar{s}'}(\mathbf{R}^d)$  and  $\psi \in C^d(P)$ , it holds*

$$B(\varphi, \psi) = \lim_{n \rightarrow \infty} \int_{\mathbf{R}^d} \varphi(\mathbf{x}) u_n(\mathbf{x}) (\mathcal{A}_{\psi_P} v_n)(\mathbf{x}) d\mathbf{x},$$

where  $\mathcal{A}_{\psi_P}$  is the Fourier multiplier operator on  $\mathbf{R}^d$  associated to  $\psi \circ \pi_P$ . The bilinear functional  $B$  can be continuously extended as a linear functional on  $L^{\bar{s}'}(\mathbf{R}^d; C^d(P))$ . ■



## Localisation principle

### Lemma

Assume that sequences  $(\mathbf{u}_n)$  and  $(\mathbf{v}_n)$  are bounded in  $L^p(\mathbf{R}^d; \mathbf{R}^r)$  and  $L^q(\mathbf{R}^d; \mathbf{R}^r)$ , respectively, and converge toward  $\mathbf{0}$  and  $\mathbf{v}$  in the sense of distributions.

Furthermore, assume that sequence  $(\mathbf{u}_n)$  satisfies:

$$\mathbf{G}_n := \sum_{k=1}^d \partial_k^{\alpha_k} (\mathbf{A}^k \mathbf{u}_n) \rightarrow \mathbf{0} \text{ in } W^{-\alpha_1, \dots, -\alpha_d; p}(\Omega; \mathbf{R}^m), \quad (3)$$

where either  $\alpha_k \in \mathbf{N}$ ,  $k = 1, \dots, d$  or  $\alpha_k > d$ ,  $k = 1, \dots, d$ , and elements of matrices  $\mathbf{A}^k$  belong to  $L^{\bar{s}'}(\mathbf{R}^d)$ ,  $\bar{s} \in (1, \frac{pq}{p+q})$ .

Finally, by  $\boldsymbol{\mu}$  denote a matrix  $H$ -distribution corresponding to subsequences of  $(\mathbf{u}_n)$  and  $(\mathbf{v}_n - \mathbf{v})$ . Then the following relation holds

$$\left( \sum_{k=1}^d (2\pi i \xi_k)^{\alpha_k} \mathbf{A}^k \right) \boldsymbol{\mu} = \mathbf{0}.$$

## Strong consistency condition

Introduce the set

$$\Lambda_{\mathcal{D}} = \left\{ \boldsymbol{\mu} \in L^{\bar{s}}(\mathbf{R}^d; (C^d(P))')^r : \left( \sum_{k=1}^n (2\pi i \xi_k)^{\alpha_k} \mathbf{A}^k \right) \boldsymbol{\mu} = \mathbf{0}_m \right\},$$

where the given equality is understood in the sense of  $L^{\bar{s}}(\mathbf{R}^d; (C^d(P))')^m$ .

Let us assume that coefficients of the bilinear form  $q$  from (2) belong to space  $L_{loc}^t(\mathbf{R}^d)$ , where  $1/t + 1/p + 1/q < 1$ .

### Definition

We say that set  $\Lambda_{\mathcal{D}}$ , bilinear form  $q$  from (2) and matrix  $\boldsymbol{\mu} = [\boldsymbol{\mu}_1, \dots, \boldsymbol{\mu}_r]$ ,  $\boldsymbol{\mu}_j \in L^{\bar{s}}(\mathbf{R}^d; (C^d(P))')^r$  satisfy the strong consistency condition if  $(\forall j \in \{1, \dots, r\}) \boldsymbol{\mu}_j \in \Lambda_{\mathcal{D}}$ , and it holds

$$\langle \phi \mathbf{Q} \otimes 1, \boldsymbol{\mu} \rangle \geq 0, \quad \phi \in L^{\bar{s}}(\mathbf{R}^d; \mathbf{R}_0^+).$$

## Compactness by compensation

**Theorem 5.** *Assume that sequences  $(\mathbf{u}_n)$  and  $(\mathbf{v}_n)$  are bounded in  $L^p(\mathbf{R}^d; \mathbf{R}^r)$  and  $L^q(\mathbf{R}^d; \mathbf{R}^r)$ , respectively, and converge toward  $\mathbf{u}$  and  $\mathbf{v}$  in the sense of distributions.*

*Assume that (3) holds and that*

$$q(\mathbf{x}; \mathbf{u}_n, \mathbf{v}_n) \rightharpoonup \omega \text{ in } \mathcal{D}'(\mathbf{R}^d).$$

*If the set  $\Lambda_{\mathcal{D}}$ , the bilinear form (2), and matrix  $H$ -distribution  $\mu$ , corresponding to subsequences of  $(\mathbf{u}_n - \mathbf{u})$  and  $(\mathbf{v}_n - \mathbf{v})$ , satisfy the strong consistency condition, then*

$$q(\mathbf{x}; \mathbf{u}, \mathbf{v}) \leq \omega \text{ in } \mathcal{D}'(\mathbf{R}^d).$$

■

## Application to the parabolic type equation

Now, let us consider the non-linear parabolic type equation

$$L(u) = \partial_t u - \operatorname{div} \operatorname{div} (g(t, \mathbf{x}, u) \mathbf{A}(t, \mathbf{x})),$$

on  $(0, \infty) \times \Omega$ , where  $\Omega$  is an open subset of  $\mathbf{R}^d$ . We assume that

$$u \in L^p((0, \infty) \times \Omega), \quad g(t, \mathbf{x}, u(t, \mathbf{x})) \in L^q((0, \infty) \times \Omega), \quad 1 < p, q,$$
$$\mathbf{A} \in L^s_{loc}((0, \infty) \times \Omega)^{d \times d}, \quad \text{where } 1/p + 1/q + 1/s < 1,$$

and that the matrix  $\mathbf{A}$  is strictly positive definite, i.e.

$$\mathbf{A} \boldsymbol{\xi} \cdot \boldsymbol{\xi} > 0, \quad \boldsymbol{\xi} \in \mathbf{R}^d \setminus \{\mathbf{0}\}, \quad (a.e. (t, \mathbf{x}) \in (0, \infty) \times \Omega).$$

Furthermore, assume that  $g$  is a Carathéodory function and non-decreasing with respect to the third variable.

Then we have the following theorem.

**Theorem 6.** *Assume that sequences  $(u_r)$  and  $g(\cdot, u_r)$  are such that  $u_r, g(u_r) \in L^2(\mathbf{R}^+ \times \mathbf{R}^d)$  for every  $r \in \mathbf{N}$ ; assume that they are bounded in  $L^p(\mathbf{R}^+ \times \mathbf{R}^d)$ ,  $p \in (1, 2]$ , and  $L^q(\mathbf{R}^+ \times \mathbf{R}^d)$ ,  $q > 2$ , respectively, where  $1/p + 1/q < 1$ ; furthermore, assume  $u_r \rightharpoonup u$  and, for some,  $f \in W^{-1, -2; p}(\mathbf{R}^+ \times \mathbf{R}^d)$ , the sequence*

$$L(u_r) = f_r \rightarrow f \quad \text{strongly in } W^{-1, -2; p}(\mathbf{R}^+ \times \mathbf{R}^d).$$

*Under the assumptions given above, it holds*

$$L(u) = f \quad \text{in } \mathcal{D}'(\mathbf{R}^+ \times \mathbf{R}^d).$$

■

## References

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