

Complex Friedrichs systems and applications



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Abstract settings

- L - complex Hilbert space (L' antidual of L),
- $\mathcal{D} \subseteq L$ - dense subspace
- $\mathcal{L}, \tilde{\mathcal{L}} : \mathcal{D} \rightarrow L$ linear unbounded operators satisfying

$$(\forall \varphi, \psi \in \mathcal{D}) \quad \langle \mathcal{L}\varphi | \psi \rangle_L = \langle \varphi | \tilde{\mathcal{L}}\psi \rangle_L, \quad (\text{T1})$$

$$(\exists c > 0)(\forall \varphi \in \mathcal{D}) \quad \|(\mathcal{L} + \tilde{\mathcal{L}})\varphi\|_L \leq c\|\varphi\|_L, \quad (\text{T2})$$

$$(\exists \mu_0 > 0)(\forall \varphi \in \mathcal{D}) \quad \langle (\mathcal{L} + \tilde{\mathcal{L}})\varphi | \varphi \rangle_L \geq 2\mu_0\|\varphi\|_L^2. \quad (\text{T3})$$



Classical complex Friedrichs operator

Let $d, r \in \mathbf{N}$, $\Omega \subseteq \mathbf{R}^d$ open and bounded with Lipschitz boundary,
 $\mathcal{D} = C_c^\infty(\Omega; \mathbf{C}^r)$, $L = L^2(\Omega; \mathbf{C}^r)$, $\mathbf{A}_k \in W^{1,\infty}(\Omega; M_r(\mathbf{C}))$, $k \in 1..d$ and
 $\mathbf{C} \in L^\infty(\Omega; M_r(\mathbf{C}))$ satisfying

$$(F1) \quad \mathbf{A}_k = \mathbf{A}_k^*$$

$$(F2) \quad (\exists \mu_0 > 0) \quad \mathbf{C} + \mathbf{C}^* + \sum_{k=1}^d \partial_k \mathbf{A}_k \geq 2\mu_0 I \quad (\text{ae on } \Omega).$$

Operators $\mathcal{L}, \tilde{\mathcal{L}} : \mathcal{D} \rightarrow L$ defined as

$$\mathcal{L}u := \sum_{k=1}^d \partial_k (\mathbf{A}_k u) + \mathbf{C}u$$

$$\tilde{\mathcal{L}}u := - \sum_{k=1}^d \partial_k (\mathbf{A}_k^* u) + (\mathbf{C}^* + \sum_{k=1}^d \partial_k \mathbf{A}_k^*)u$$

satisfy (T1)–(T3).



Operator \mathcal{L} is called the **symmetric positive operator** or the **Friedrichs operator** and

$$\mathcal{L}u = f$$

the **symmetric positive system** or the **Friedrichs system**.

- introduced in K. O. Friedrichs: Symmetric positive linear differential equations, Communications on Pure and Applied Mathematics **11** (1958), 333-418
- goal: treating the equations of mixed type, such as the Tricommi equation

$$y \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0,$$

unified tretment of equations and systems of different type

- convenient for the numerical treatment



Formulation of the problem

- $(\mathcal{D}, \langle \cdot | \cdot \rangle_{\mathcal{L}})$ is an inner product space, where

$$\langle \cdot | \cdot \rangle_{\mathcal{L}} := \langle \cdot | \cdot \rangle_L + \langle \mathcal{L} \cdot | \mathcal{L} \cdot \rangle_L.$$

- $\| \cdot \|_{\mathcal{L}}$ is called the **graph norm**.
- W_0 - the completion of \mathcal{D} in the graph norm ... $\mathcal{L}, \tilde{\mathcal{L}} \in \mathcal{L}(L; W_0')$

Lemma

The **graph space**

$$W := \{u \in L : \mathcal{L}u \in L\} = \{u \in L : \tilde{\mathcal{L}}u \in L\}$$

is Hilbert space with respect to $\langle \cdot | \cdot \rangle_{\mathcal{L}}$.

Problem: for given $f \in L$ find $u \in W$ such that $\mathcal{L}u = f$.

Find sufficient conditions on $V \leq W$ such that $\mathcal{L}|_V : V \rightarrow L$ is an isomorphism.



Boundary operator

Boundary operator $D \in \mathcal{L}(W; W')$ is defined by

$${}_{W'}\langle Du, v \rangle_W := \langle \mathcal{L}u \mid v \rangle_L - \langle u \mid \tilde{\mathcal{L}}v \rangle_L \quad u, v \in W.$$

Lemma

Under assumptions (T1)–(T2), operator D is selfadjoint

$${}_{W'}\langle Du, v \rangle_W = \overline{{}_{W'}\langle Dv, u \rangle_W}$$

and satisfies

$$\ker D = W_0$$

$$\operatorname{im} D = W_0^0 := \{g \in W' : (\forall u \in W_0) \quad {}_{W'}\langle g, u \rangle_W = 0\}.$$

In particular, $\operatorname{im} D$ is closed in W' .



Well-posedness theorem

Let V and \tilde{V} be subspaces of W that satisfy

$$\begin{aligned} (\forall u \in V) \quad {}_{W'}\langle Du, u \rangle_W &\geq 0 \\ (\forall v \in \tilde{V}) \quad {}_{W'}\langle Dv, v \rangle_W &\leq 0 \end{aligned} \tag{V1}$$

$$V = D(\tilde{V})^o, \quad \tilde{V} = D(V)^o. \tag{V2}$$

Theorem

Under assumptions (T1)–(T3) and (V1)–(V2), the operators $\mathcal{L}|_V : V \rightarrow L$ and $\tilde{\mathcal{L}}|_{\tilde{V}} : \tilde{V} \rightarrow L$ are isomorphisms.¹

¹In real case: [AE&JLG&GC2007].



Non-stationary complex Friedrichs systems

Consider abstract Cauchy problem

$$\begin{cases} u'(t) + \mathcal{L}u(t) = f \\ u(0) = u_0, \end{cases}$$

where $u : [0, T) \rightarrow L$, $T > 0$ is the unknown function, $f : \langle 0, T \rangle \rightarrow L$, $u_0 \in L$ and \mathcal{L} is abstract Friedrichs operator that satisfy (T1)–(T2) and

$$(\forall \varphi \in \mathcal{D}) \quad \operatorname{Re} \left\langle (\mathcal{L} + \tilde{\mathcal{L}})\varphi \mid \varphi \right\rangle_L \geq 0. \quad (\text{T3}')$$

Let $V \leq W$ satisfy (V1)–(V2). Then following is valid

Theorem

$-\mathcal{L}|_V$ is the infinitesimal generator of a contraction C_0 -semigroup $(T(t))_{t \geq 0}$ on L .²

²In real case: [BE2016].



Theorem

Let \mathcal{L} be an operator that satisfy (T1)–(T2) and (T3'), V subspace of its graph space satisfying (V1)–(V2), and $f \in L^1(\langle 0, T \rangle; L)$. Then for every $u_0 \in L$ Cauchy problem

$$\begin{cases} u'(t) + \mathcal{L}u(t) = f \\ u(0) = u_0 \end{cases}$$

has the unique weak solution $u \in C([0, T]; L)$ given by

$$u(t) = T(t)u_0 + \int_0^t T(t-s)f(s) ds, \quad t \in [0, T],$$

where $(T(t))_{t \geq 0}$ is a contraction C_0 -semigroup generated with $-\mathcal{L}|_V$.



Friedrichs systems in H^s spaces

Let $s \in \mathbf{R}$, $L = H^s(\mathbf{R}^d; \mathbf{C}^r)$, $\mathcal{D} = C_c^\infty(\mathbf{R}^d; \mathbf{C}^r)$ and assume that constant matrices \mathbf{C} , \mathbf{A}_k , $k \in 1..d$, satisfy (F1) and (F2):

$$\mathbf{A}_k = \mathbf{A}_k^* ,$$

$$(\exists \mu_0 > 0) \quad \mathbf{C} + \mathbf{C}^* \geq 2\mu_0 \mathbf{I} \quad (\text{ae on } \Omega) .$$

Operators

$$\mathcal{L}u := \sum_{k=1}^d \partial_k (\mathbf{A}_k u) + \mathbf{C}u$$

and

$$\tilde{\mathcal{L}}u := - \sum_{k=1}^d \partial_k (\mathbf{A}_k u) + \mathbf{C}^* u$$

satisfy (T1)–(T3), boundary operator D is trivial and $V = \tilde{V} = W$.



Linear Dirac system

Consider system of equations

$$\gamma^0 \partial_t \psi + \gamma^1 \partial_1 \psi + \gamma^2 \partial_2 \psi + \gamma^3 \partial_3 \psi + \mathbf{B} \psi = \mathbf{f}, \quad (1)$$

where $\psi : [0, T) \times \mathbf{R}^3 \rightarrow \mathbf{C}^4$ is unknown function, $\mathbf{f} : \langle 0, T \rangle \rightarrow \mathbf{C}^4$,

$\mathbf{B} = \begin{bmatrix} b_1 \mathbf{I} & 0 \\ 0 & b_2 \mathbf{I} \end{bmatrix}$ for $b_1, b_2 : \mathbf{R}^3 \rightarrow \mathbf{C}$ and 2×2 unit matrix \mathbf{I} , while

$$\gamma^0 = \begin{bmatrix} \mathbf{I} & 0 \\ 0 & -\mathbf{I} \end{bmatrix}, \quad \gamma^k = \begin{bmatrix} 0 & \sigma^k \\ -\sigma^k & 0 \end{bmatrix}, \quad k = 1, 2, 3.$$

$$\sigma^1 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad \sigma^2 = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}, \quad \sigma^3 = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$



System (1) can be written as Friedrichs system

$$\partial_t \psi + \mathcal{L}\psi = F,$$

where $F = \gamma^0 f$ and $\mathcal{L}\psi = \sum_{k=1}^3 \mathbf{A}_k \partial_k \psi + \mathbf{C}\psi$ for

$$\mathbf{A}_k = \tilde{\mathbf{A}}_k := \begin{bmatrix} 0 & \sigma^k \\ \sigma^k & 0 \end{bmatrix}, \quad \mathbf{C} = \gamma^0 \mathbf{B}.$$

Spaces involved:

$$\mathcal{D} = C_c^\infty(\mathbf{R}^3; \mathbf{C}^4)$$

$$L = L^2(\mathbf{R}^3; \mathbf{C}^4), \text{ (or } H^s(\mathbf{R}^3; \mathbf{C}^4)\text{)}$$

$$W = \left\{ u \in L^2(\mathbf{R}^3; \mathbf{C}^4) : \sum_{k=1}^3 \mathbf{A}_k \partial_k u \in L^2(\mathbf{R}^3; \mathbf{C}^4) \right\}$$

D is trivial, $V = \tilde{V} = W$.



Dirac-Klein-Gordon system

$$\begin{cases} -i(\gamma^0 \partial_t + \gamma^1 \partial_1 + \gamma^2 \partial_2 + \gamma^3 \partial_3 + M)\psi = \phi\psi \\ \partial_t^2 \phi - \Delta \phi + m^2 \phi = \psi^* \gamma^0 \psi \end{cases} \quad (2)$$

where unknown functions are $\psi = \psi(t, x) : \mathbf{R}^{1+3} \rightarrow \mathbf{C}^4$ and $\phi : \mathbf{R}^{1+3} \rightarrow \mathbf{R}$, while $M, m \geq 0$ and $\gamma^k, k = 1..3$ are same as in previous example.

Remark

For two Friedrichs systems

$$\begin{aligned} \partial_t \mathbf{u}_1 + \mathcal{L}_1 \mathbf{u}_1 &= \mathbf{f}_1 \\ \partial_t \mathbf{u}_2 + \mathcal{L}_2 \mathbf{u}_2 &= \mathbf{f}_2 \end{aligned}$$

system

$$\partial_t \mathbf{u} + \mathcal{L} \mathbf{u} = \mathbf{f}$$

is also a Friedrichs system with $\mathcal{L} = \begin{bmatrix} \mathcal{L}_1 & 0 \\ 0 & \mathcal{L}_2 \end{bmatrix}$, $\mathbf{u} = \begin{bmatrix} \mathbf{u}_1 \\ \mathbf{u}_2 \end{bmatrix}$, $\mathbf{f} = \begin{bmatrix} \mathbf{f}_1 \\ \mathbf{f}_2 \end{bmatrix}$.



First system of equations in (2) can be written as

$$\partial_t \psi + \mathcal{L}_1 \psi = \mathbf{f}_1$$

where $\mathcal{L}_1 \psi = \sum_{k=1}^3 \tilde{\mathbf{A}}_k \partial_k \psi + \mathbf{C}_1 \psi$ with $\tilde{\mathbf{A}}_k$ as in previous example and

$$\mathbf{C}_1 = \begin{bmatrix} iM\mathbf{I} & 0 \\ 0 & -iM\mathbf{I} \end{bmatrix}, \mathbf{f}_1 = i\gamma^0 \psi \phi.$$

For the second system of equations in (2) we introduce

$$\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} \phi \\ \partial_t \phi \\ -\nabla \phi \end{bmatrix}$$

in order to get an evolution Friedrichs system

$$\partial_t \mathbf{v} + \mathcal{L}_2 \mathbf{v} = \mathbf{f}_2,$$



where $\mathcal{L}_2 v = \sum_{k=1}^3 \partial_k \bar{A}_k v + C_2 v$ with

$$\bar{A}_1 = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \bar{A}_2 = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \bar{A}_3 = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \end{bmatrix}$$

$$C_2 = \begin{bmatrix} 0 & -1 & 0 & 0 & 0 \\ m^2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{and} \quad f_2 = \begin{bmatrix} 0 \\ |u_1|^2 + |u_2|^2 - |u_3|^2 - |u_4|^2 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$



Using block diagonal structure, we get evolution Friedrichs system

$$\partial_t \mathbf{u} + \mathcal{L} \mathbf{u} = \mathbf{f},$$

where $\mathbf{u} = [\psi \quad \mathbf{v}]^\top$, \mathcal{L} is Friedrichs operator with $\mathbf{A}_k = \begin{bmatrix} \tilde{\mathbf{A}}_k & 0 \\ 0 & \bar{\mathbf{A}}_k \end{bmatrix}$,

$\mathbf{C} = \begin{bmatrix} \mathbf{C}_1 & 0 \\ 0 & \mathbf{C}_2 \end{bmatrix}$ and $\mathbf{f} = [f_1 \quad f_2]^\top$. Spaces involved:

$$L = H^2(\mathbf{R}^3; \mathbf{C}^9),$$

$$W = \{\psi \in H^2(\mathbf{R}^3; \mathbf{C}^9) : \mathcal{L}_1 \psi \in H^2(\mathbf{R}^3; \mathbf{C}^4)\} \times H^2(\mathbf{R}^3) \times H^2(\mathbf{R}^3) \times H^2_{\text{div}}(\mathbf{R}^3; \mathbf{C}^3).$$

Moreover, \mathbf{f} is Lipschitz on $H^2(\mathbf{R}^3; \mathbf{C}^9)$ and D is trivial.



Dirac-Maxwell system

$$\begin{cases} -\frac{i}{2\pi}(\gamma^0 \partial_t + \gamma^1 \partial_1 + \gamma^2 \partial_2 + \gamma^3 \partial_3)\psi + m\beta\psi = \sum_{k=0}^3 \mathcal{A}_k \gamma^k \psi \\ (-\frac{\partial^2}{\partial t^2} + \Delta)\mathcal{A}_k = -\gamma^k \psi \cdot \psi, \quad k = 0..3, \end{cases} \quad (3)$$

where $\gamma^0 = \mathbf{I}$ and γ^k , $k = 1, 2, 3$ as before. Unknown functions are $\psi : \mathbf{R}^{1+3} \rightarrow \mathbf{C}^4$ and $\mathcal{A} = [\mathcal{A}_0 \quad \mathcal{A}_1 \quad \mathcal{A}_2 \quad \mathcal{A}_3]^\top$, while $m \geq 0$ and $\beta = \begin{bmatrix} \mathbf{I} & 0 \\ 0 & -\mathbf{I} \end{bmatrix}$. Analog procedure as in previous example gives us Friedrichs system

$$\partial_t \mathbf{u} + \mathcal{L} \mathbf{u} = \mathbf{F},$$

$$\text{where } \mathbf{u} = \begin{bmatrix} \psi \\ v_0 \\ v_1 \\ v_2 \\ v_3 \end{bmatrix}, \quad v_k = \begin{bmatrix} \mathcal{A}_k \\ \partial_t \mathcal{A}_k \\ -\nabla \mathcal{A}_k \end{bmatrix}, \quad f_k = \begin{bmatrix} 0 \\ \gamma^k \psi \cdot \psi \\ 0 \\ 0 \\ 0 \end{bmatrix}, \quad k = 0..3$$



Operator \mathcal{L} is Friedrichs operator with $\mathbf{C} = \begin{bmatrix} \tilde{\mathbf{C}} & 0 \\ 0 & 0 \end{bmatrix} \in M_{24}(\mathbf{C})$,

$$\tilde{\mathbf{C}} = \begin{bmatrix} 2\pi im & 0 \\ 0 & -2\pi im \end{bmatrix} \text{ and}$$

$$\mathbf{A}_k = \begin{bmatrix} \tilde{\mathbf{A}}_k & 0 & 0 & 0 & 0 \\ 0 & \bar{\mathbf{A}}_k & 0 & 0 & 0 \\ 0 & 0 & \bar{\mathbf{A}}_k & 0 & 0 \\ 0 & 0 & 0 & \bar{\mathbf{A}}_k & 0 \\ 0 & 0 & 0 & 0 & \bar{\mathbf{A}}_k \end{bmatrix}, \quad k = 1, 2, 3.$$

$$\mathbf{F} = \left[\sum_{k=0}^3 \mathcal{A}_k \gamma^k \psi \quad f_0 \quad f_1 \quad f_2 \quad f_3 \right]^\top. \text{ Spaces involved:}$$

$$L = H^2(\mathbf{R}^3; \mathbf{C}^{24}),$$

$$W = \{ \psi \in H^2(\mathbf{R}^3) : \bar{A}_1 \partial_1 \psi + \bar{A}_2 \partial_2 \psi + \bar{A}_3 \partial_3 \psi \in H^2(\mathbf{R}^3) \} \times [H^2(\mathbf{R}^3) \times H^3(\mathbf{R}^3) \times H^2_{\text{div}}(\mathbf{R}^3)]^4.$$



Thank you for your attention!